

A Normative Theory of Decision-making From Multiple Stimuli



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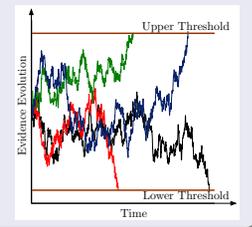
Drift Diffusion Model and the Two Alternative Forced Choice Tasks

- Models human decision making in two alternative choice tasks
- Evidence evolution in a two alternative choice task is modeled by

$$dx(t) = \beta dt + dW(t), \quad x(t) = x_0$$

- Decision process at time τ is

$$\begin{cases} x(\tau) > \eta, & \text{choose alternative 1,} \\ x(\tau) < -\eta, & \text{choose alternative 2,} \\ \text{else,} & \text{collect more evidence.} \end{cases}$$

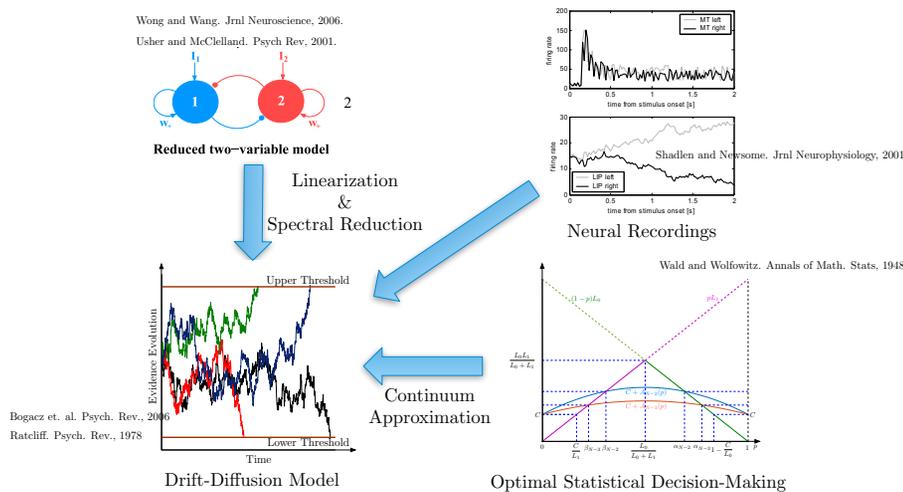


- Threshold dictates the speed-accuracy trade-off**

- The Ornstein-Uhlenbeck process has an additional $-\lambda x dt$ term in the above SDE

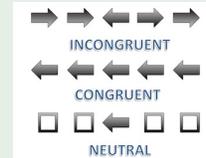
Bogacz et. al. The physics of optimal decision making: A formal analysis of performance in two-alternative forced choice tasks. Psych Rev, 2006

DDM connects several approaches to model decision-making



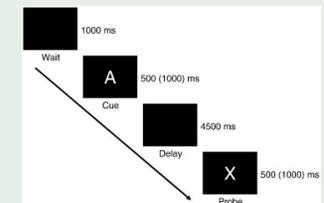
Slightly More Complex Two Alternative Choices Tasks

Eriksen-Flanker Task



- Congruent stimulus**— call for the same response as the target
- Incongruent stimulus**— call for the opposite response of the target
- Response rule:** Respond per the target stimuli

AX-CPT Task



- Cue stimulus** – A or B
- Probe stimulus** – X or Y
- Symmetric Response Rule:** Click left if AX or BY and right o/w
- AX condition happens 50% of the times
- Others: AY– 20%, BX– 20%, BY– 10%

A Bayesian Perspective on Multiple Stimuli Integration in AX-CPT

- For now, assume context and target appear together
- Suppose context (A or B) can be sampled independently of target (X or Y)
- Let e_τ^c and e_τ^g be the log-likelihood ratios at time τ of A v/s B and X v/s Y, resp.
- Let $\pi_{AX}, \pi_{AY}, \pi_{BX}$ and π_{BY} be the prior probabilities of four conditions



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- Let $\pi_{AX}, \pi_{AY}, \pi_{BX}$ and π_{BY} be the prior probabilities of four conditions
- Then, the log-likelihood ratio of responding left and responding right is

$$Z_t = \log \frac{\mathbb{P}(AX \text{ or } BY | e_{1:t}^c, e_{1:t}^g)}{\mathbb{P}(AY \text{ or } BX | e_{1:t}^c, e_{1:t}^g)} = \log \frac{\pi_{AX} \exp(z_t^c) \exp(z_t^g) + \pi_{BY}}{\pi_{AY} \exp(z_t^c) + \pi_{BX} \exp(z_t^g)},$$

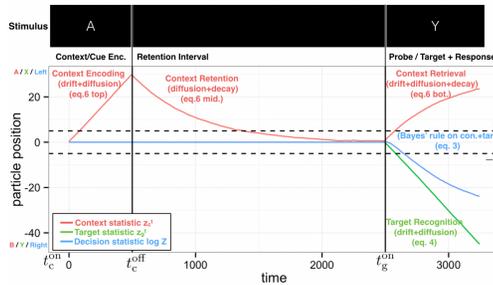
where $z_t^g = \sum_{\tau=1}^t e_\tau^g$ and $z_t^c = \sum_{\tau=1}^t e_\tau^c$.

- z_t^g and z_t^c are aggregate log-likelihood ratios and converge to DDM in continuum limit



A Bayesian Perspective on Multiple Stimuli Integration in AX-CPT II

- Now, context and target may appear at different times



$$0 \leq t \leq t_c^{\text{off}}$$

$$dz^c = \bar{a}_c dt + dW$$

$$z^g(t) = z_0^g$$

$$t_c^{\text{off}} \leq t \leq t_g^{\text{on}}$$

$$dz^c = -\lambda_f z^c dt + dW$$

$$z^g(t) = z_0^g$$

$$t > t_g^{\text{on}}$$

$$dz^c = (-\lambda_f z^c + a_c) dt + dW$$

$$dz^g = a_g dt + dW$$



Fixed Threshold Policy: Compare Z_t with fixed thresholds $\pm\theta$.

A 2D Integration Perspective on AX-CPT

$$t > t_g^{\text{on}}$$

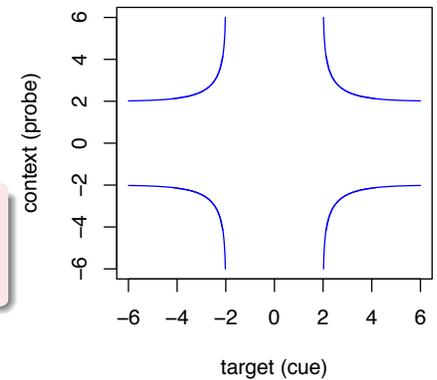
$$dz^c = (-\lambda_f z^c + a_c) dt + dW$$

$$dz^g = a_g dt + dW$$

$$Z_t = \pm\theta \Rightarrow$$

$$\exp(\mp\theta) (\pi_{AX} \exp(z_t^c) \exp(z_t^g) + \pi_{BY}) = \pi_{AY} \exp(z_t^c) + \pi_{BX} \exp(z_t^g)$$

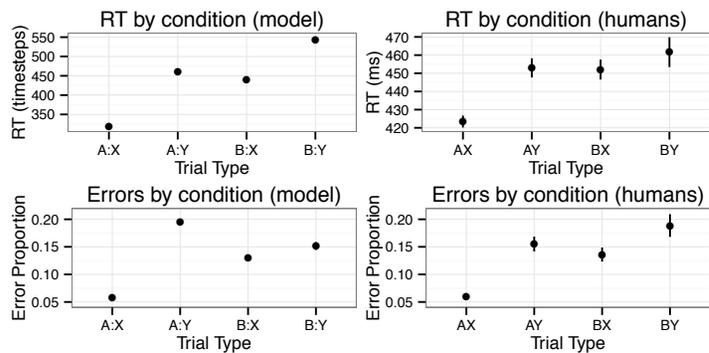
AX-CPT



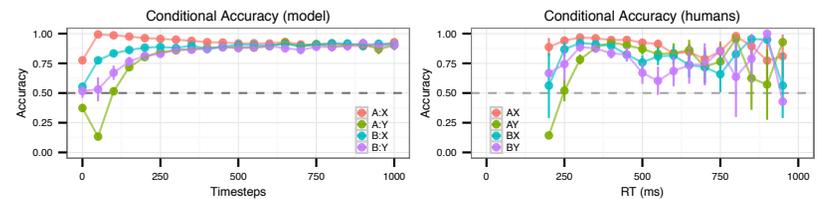
2D LCA in disguise with boundaries determined by the task and response rule



Model Predicts AXCPT Behavioral Data



Model Predicts Signature AXCPT Behavior



- A region of below-chance performance early in AY trials but not other trials
- Below chance performance in AY trials due to a high AX prior in AX-CPT
- Model predicts lower accuracy in early B* trials: possibly due to global left response bias



A Normative Account of Proactive and Reactive Control

Braver (2012): Dual Mechanisms of Control.

“Proactive” control:

- effortful maintenance of context / task rules.
- errors based on misidentifying X/Y (more AY than BX errors)

“Reactive” control:

- usage of target stimulus as cue for memory retrieval
- errors based on misremembering A/B (more BX than AY errors)

Lositsky et al. 2015

Proactive strategy with bad memory looks reactive, reactive strategy with bad perception looks proactive



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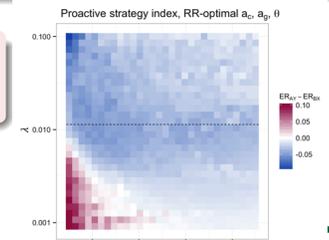
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- Explore threshold θ and drift rates a_c and a_g that maximize the reward rate ($= \frac{1-ER}{RT}$) for fixed $a_c + a_g$
- Proactive strategies are observed for low λ and $a_c + a_g$

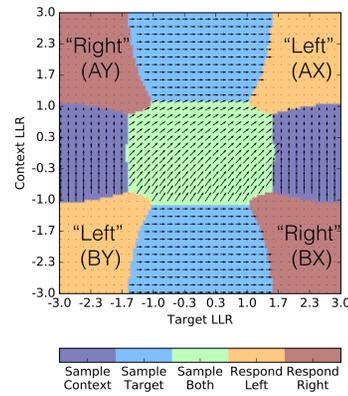


What is the optimal decision rule?

- Cost Structure:

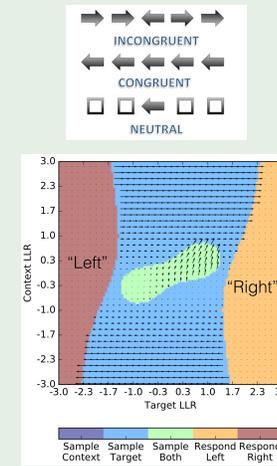
- c_1 , sample only the context,
- c_2 , sample only the target,
- $c_1 + c_2 - \epsilon$, sample both target and context,
- l_1 , click left erroneously,
- l_2 , click right erroneously.

- Solve the POMDP using backward induction
- Fixed threshold policies only optimal in some limiting cases

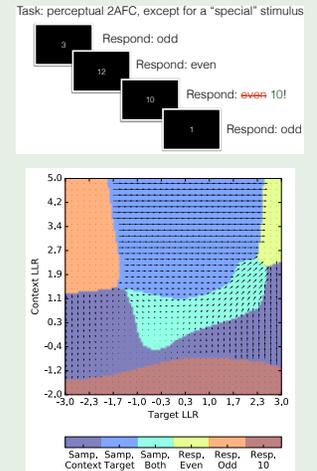


Other Behavioral Tasks

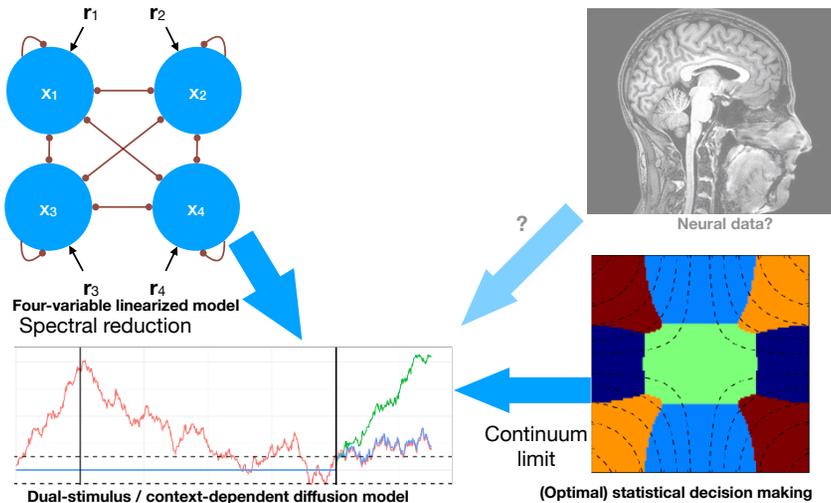
Eriksen-Flanker Task



Prospective Memory Task



CDDM as a Unifying Model for Multiple Stimuli Decision Making



Recap

- A normative theory based on Bayesian inference for two-stimuli decision-making
- Can model several TAFD tasks with contextual information including, Eriksen-Flanker, AXCTP, Prospective memory tasks
- A 2d diffusion model in which the context sets threshold for target and vice-versa
- Model captures behavioral signatures in these tasks
- Fixed-threshold policies need not be Bayes-optimal in the SPRT sense
- In some limits, the CDDM unifies the PDP model and the Bayes-optimal model

Acknowledgment and References



Mike Shvartsman



Narayanan Sundaram



Jonathan Cohen

References:

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- 2 M. Shvartsman, V. Srivastava, N. Sundaram, and J. D. Cohen. **Using Behavior to Decode Allocation of Attention in Context Dependent Decision Making.** *Proceedings of the International Conference on Cognitive Modeling*, University Park, PA, pages 65-71, 2016.
- 3 M. Shvartsman, V. Srivastava, and J. D. Cohen. **Exploring Fixed-Threshold and Optimal Policies in Multi-alternative Decision Making.** *Multidisciplinary Conf. on Reinforcement Learning and Decision Making*, June 2017.

