

ECE 366 HW # 3

Fall 2008

Solutions

$$(1) a) \frac{\sin t}{t^2 + 2} \delta(t) = 0$$

$$b) \frac{\sin\left[\frac{\pi}{2}(t-2)\right]}{t^2 + 4} \delta(1-t) = \frac{\sin\left[-\frac{\pi}{2}\right]}{5} \delta(1-t)$$

$$= \frac{-1}{5} \delta(1-t)$$

$$c) \int_{-\infty}^{\infty} x(\tau) \delta(t-\tau) d\tau = x(t)$$

$$d) \int_{-\infty}^{\infty} \sin(\pi t) \delta(2t-3) dt = \frac{1}{2} \int_{-\infty}^{\infty} \sin(\pi t) \delta\left(t - \frac{3}{2}\right) dt$$

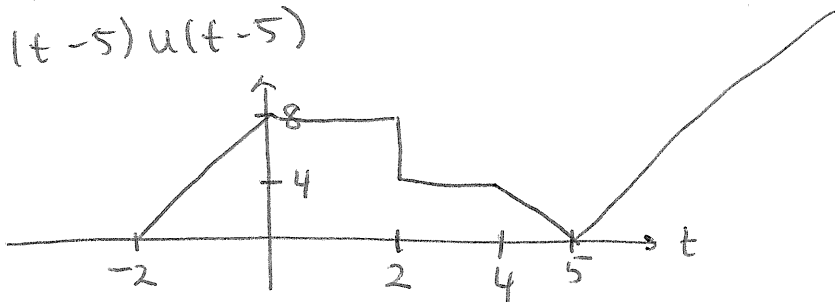
$$= \frac{1}{2} \sin\left(\frac{3\pi}{2}\right) = -\frac{1}{2}$$

$$e) \int_{-\infty}^t e^{-\tau} \delta(\tau) d\tau = \begin{cases} 0 & \text{if } t < 0 \\ e^{-0} & \text{if } t \geq 0 \end{cases} = u(t)$$

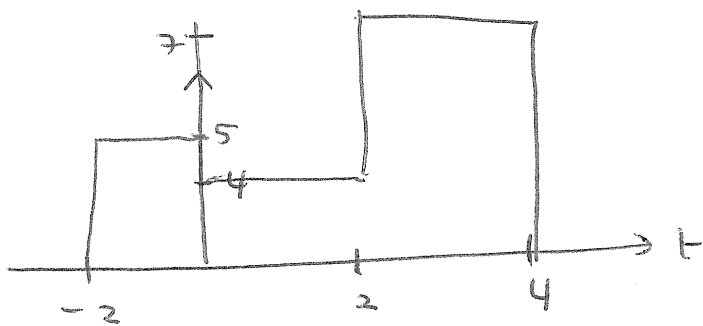
$$f) \int_{-\infty}^{\infty} e^{x-1} \cos\left[\frac{\pi}{2}(x-5)\right] \delta(x-3) dx$$

$$= e^2 \cos\left[\frac{\pi}{2}(-2)\right] = e^2 \cos[-\pi] = -e^2$$

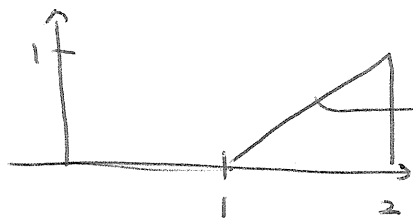
$$(2) a) x(t) = 4(t+2)u(t+2) - 4t u(t) - 4u(t-2) - u(t-4)u(t-4) + 4(t-5)u(t-5)$$



$$b) x(t) = 5u(t+2) - u(t) + 3u(t-2) - 7u(t-4)$$



(3) a) P. 1.1-2d



$$(t-1)[u(t-1) - u(t-2)]$$

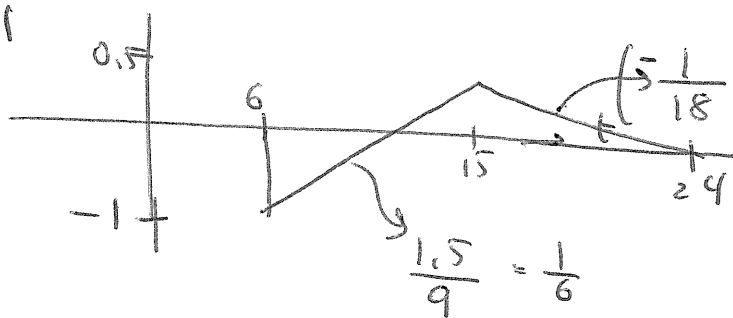
$$= (t-1)u(t-1) - (t-1)u(t-2)$$

$$= r(t-1) - (t-2+1)u(t-2)$$

$$= r(t-1) - (t-2)u(t-2) - u(t-2)$$

$$= r(t-1) - r(t-2) - u(t-2)$$

b) P 1.2-1

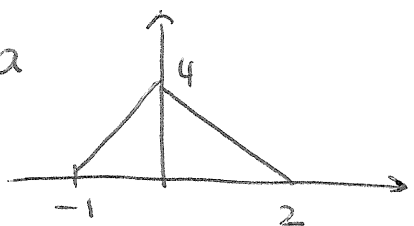


$$\left(\frac{5}{18}t + \frac{4}{3}\right)[u(t-15) - u(t-24)]$$

$$\left(\frac{1}{6}t - 2\right)[u(t-6) - u(t-15)]$$

$$\left(\frac{1}{6}t - 2\right)[u(t-6) - u(t-15)] + \left(\frac{5}{18}t + \frac{4}{3}\right)[u(t-15) - u(t-24)]$$

c) P 1.4-2a



$$(4t+4)[u(t+1) - u(t)] + (-2t+4)[u(t) - u(t-2)]$$

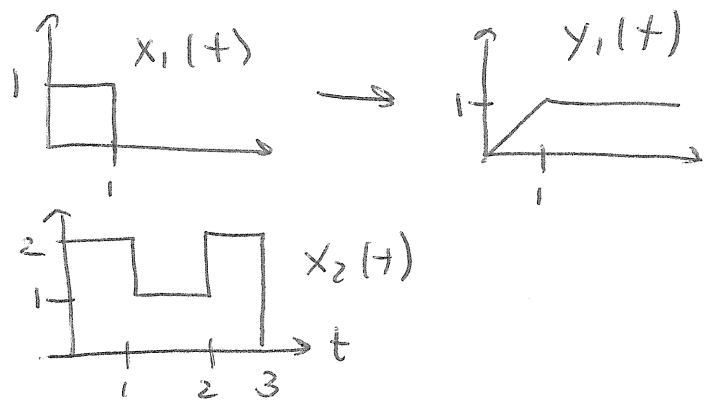
$$= 4(t+1)u(t+1) - 4(t+1)u(t) + u(t) - u(t-2)$$

$$- 2(t-2)u(t) + 2(t-2)u(t-2)$$

$$= 4r(t+1) + 2r(t-2) - 4r(t) - 4u(t) - 2r(t) + 4u(t)$$

$$= 4r(t+1) - 6r(t) + 2r(t-2)$$

④ 1.7-13



- a) Is $x_2(t) = 2x_1(3t) - x_1(t-1)$? No
 $x_2(t) = 2x_1(t) + x_1(t-1) + 2x_1(t-2)$
- b) $y_2(t) = 2y_1(t) + y_1(t-1) + 2y_1(t-2)$

⑤ a) $y(t) = \int_{-\infty}^t x(z) dz$

- Linear: $\int_{-\infty}^t (a_1 x_1(z) + a_2 x_2(z)) dz$
 $= a_1 \int_{-\infty}^t x_1(z) dz + a_2 \int_{-\infty}^t x_2(z) dz$
 $= a_1 y_1(t) + a_2 y_2(t) \checkmark$ Linear.

- Time-Invariance: $x(t) \xrightarrow{\text{Delay}} x(t-t_0) \xrightarrow{T} \int_{-\infty}^t x(z-t_0) dz$
 $\int_{-\infty}^{t-t_0} x(z) dz$

$x(t) \xrightarrow{T} \int_{-\infty}^t x(z) dz \xrightarrow{\text{Delay}} \int_{-\infty}^{t-t_0} x(z) dz$

Time Invariant

- Not instantaneous (depends on the past)
- Causal
- $\frac{dy(t)}{dt} = x(t)$ invertible
- Stable? No $|y(t)| \leq \int_{-\infty}^t |x(z)| dz \leq M t \rightarrow \infty$



b) $y(t) = x(at) \quad a > 1$

Linearity: $a_1 x_1(at) + a_2 x_2(at)$

Yes \rightarrow Linear.

Time Invariance: $x(t) \xrightarrow{\text{Delay}} x(t-t_0) \xrightarrow{T} x(at-t_0) \neq$
 $x(t) \xrightarrow{T} x(at) \xrightarrow{\text{Delay}} x(a(t-t_0))$

Time varying

Instantaneous: No y can depend on the past

Causal: Yes (does not depend on the future)

Invertible: $y(\frac{t}{a}) = x(t)$ Yes.

Stable: if $|x(t)| \leq M \rightarrow |y(t)| = |x(at)| \leq M$
 BIBO stable

c) $y(t) = x(t)tu(t)$

- $T[a_1 x_1(t) + a_2 x_2(t)] = (a_1 x_1(t) + a_2 x_2(t))tu(t)$
 $= a_1 t x_1(t)u(t) + a_2 t x_2(t)u(t)$
 $= a_1 y_1(t) + a_2 y_2(t)$

Linear

- Time Invariance:

$x(t) \xrightarrow{\text{Delay}} x(t-t_0) \xrightarrow{T} t x(t-t_0)u(t) \neq$
 $x(t) \xrightarrow{T} x(t)tu(t) \xrightarrow{\text{Delay}} x(t-t_0)(t-t_0)u(t-t_0)$

Time varying

- Instantaneous: Yes

- Causal: Yes

- Invertible: $x(t) = \frac{y(t)}{tu(t)}$ \leftarrow divide by zero for $t < 0$
 No. not well-defined

- Stability: if $|x(t)| \leq M$

$\rightarrow |y(t)| = |x(t)| \underbrace{|t| |u(t)|}_{\leq 1} \leq M |t| \rightarrow \infty$

not BIBO stable.

$$d) y(t) = e^{x(t)}$$

$$\text{Linearity: } T[a_1 x_1(t) + a_2 x_2(t)]$$

$$= e^{(a_1 x_1(t) + a_2 x_2(t))} = e^{a_1 x_1(t)} \cdot e^{a_2 x_2(t)}$$

$$\neq a_1 y_1(t) + a_2 y_2(t)$$

Nonlinear

$$\text{Time invariance: } x(t) \xrightarrow{\text{Delay}} x(t-t_0) \xrightarrow{T} e^{x(t-t_0)}$$

$$x(t) \xrightarrow{T} e^{x(t)} \xrightarrow{\text{Delay}} e^{x(t-t_0)}$$

Time Invariant

- Instantaneous: Yes

- Causal: Yes

- Invertible: $x(t) = \ln y(t) \rightarrow \text{Yes}$

- Stable: if $|x(t)| \leq M \rightarrow |y(t)| = |e^{x(t)}|$

$$= e^{x(t)} \leq e^M < \infty$$

BIBO stable