

$$L(s) = \frac{N(s)}{D(s)}$$

$$\deg(N) = \deg(D)$$

eg.

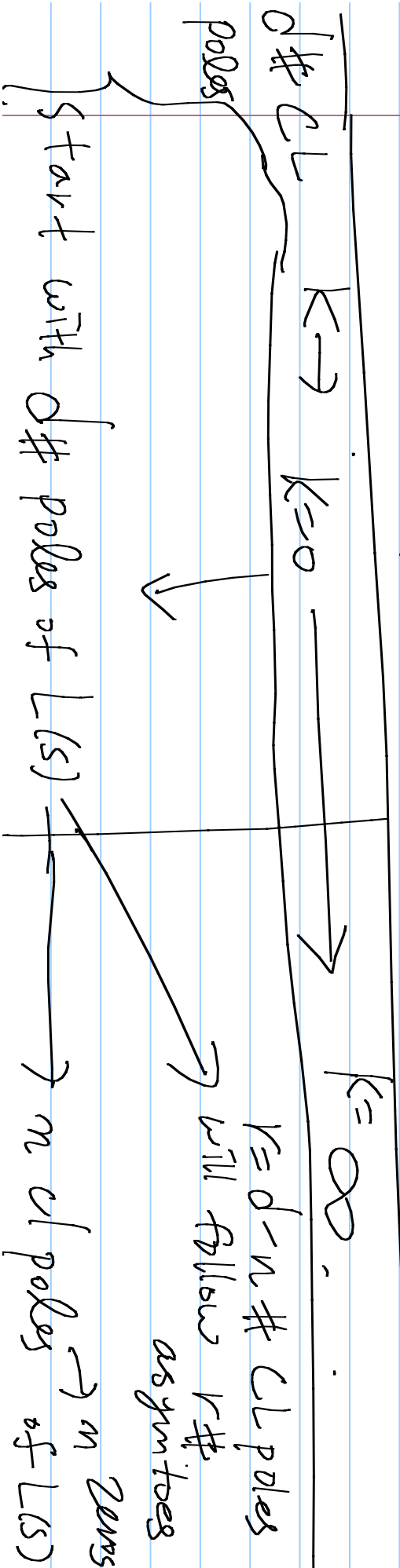
$$\frac{(s+1)}{(s+2)(s+3)}$$

$$\deg(N) = 1 = \textcircled{n}$$

$$\text{eg. } \deg(\text{den}) = \deg(D)$$

$$\deg(D) = 2 = d \Rightarrow d \# \text{ CL poles}$$

$$r = 2 - 1$$



$$L(s) = \frac{(s-z_1)(s-z_2)}{(s-p_1)(s-p_2)(s-p_3)} = \frac{r_1 e^{j\theta_1} \cdot r_2 e^{j\theta_2}}{r_{p1} e^{j\theta_{p1}} \cdot r_{p2} e^{j\theta_{p2}} \cdot r_{p3} e^{j\theta_{p3}}}$$

$L(s) = r^* e^{j\theta^*}$

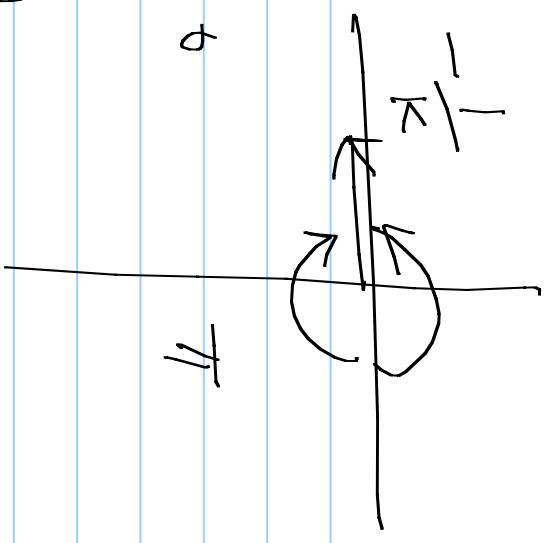
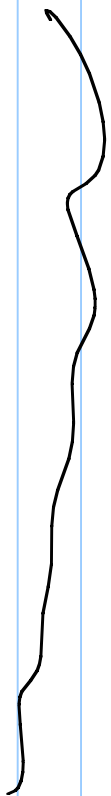
$$\rightarrow \text{mag}(L(s)) = r^* = \frac{r_{z1} \cdot r_{z2}}{r_{p1} \cdot r_{p2} \cdot r_{p3}}$$

$$\angle L(s) = \theta^* = \theta_{z1} + \theta_{z2} - \theta_{p1} - \theta_{p2} - \theta_{p3}$$

$$CE: 1 + K L(s) = 0$$

$$\angle L(s) = \angle \left(-\frac{1}{K} \right) = 180^\circ$$

$$\angle L(s) = 180^\circ, (-180^\circ)$$



$$L(s) = \frac{(s - z_1)}{(s - p_1) \cdot (s - p_2)}$$

$$= \frac{r_{z_1} \cdot e^{j\theta_{z_1}}}{r_{p_1} e^{j\theta_{p_1}} \cdot r_{p_2} e^{j\theta_{p_2}}}$$

$$= \frac{r_{z_1}}{r_{p_1} \cdot r_{p_2}} \cdot e^{j(\theta_{z_1} - \theta_{p_1} - \theta_{p_2})}$$

$$= r^* e^{j\theta^*}$$

$$\angle L(s) = \theta^* = \theta_{z_1} - \theta_{p_1} - \theta_{p_2}$$

$$\text{mag}(L(s)) = r^* = \frac{r_{z_1}}{r_{p_1} \cdot r_{p_2}}$$

$$L(s) = \frac{s+1}{s^2+s+1}$$

$$= \frac{s}{s^2} + \frac{1}{s^2}$$

$$\textcircled{1} + \cancel{\frac{s}{s^2}} + \cancel{\frac{1}{s^2}}$$

$$\approx \frac{1}{s} + \cancel{\frac{1}{s^2}} \approx \frac{1}{s}$$

s $r=1$ $n_0=1$

$$\frac{1}{100} + \frac{1}{10000} \quad s=100$$

$$\approx \underline{0.01} + \cancel{0.0001} \approx \frac{1}{100}$$

$$s = m \cdot e^{j\theta}$$

$$s^r = \underbrace{(m \cdot e^{j\theta}) (m \cdot e^{j\theta}) \dots (m \cdot e^{j\theta})}_{r \text{ times}}$$

$$s = m e^{j\theta}$$

$$= m^r e^{j\theta r}$$

$$\underline{s^r} = \underline{m^* e^{j\theta^*}}$$

$$\angle s^r = \theta^* \quad \angle s = \theta$$

$$r\theta = \theta^*$$

$$\angle s =$$

$$\boxed{\frac{\theta^*}{r}}$$