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# WIRELESS SENSOR NETWORK HEALTH DIAGNOSTIC

FINAL REPORT

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## EXECUTIVE SUMMARY

The Air Force Research Laboratory has proposed a project of developing a diagnostic tool to best determine the health of a wireless sensor network. The main objective of the project was to scientifically determine the best set of metrics that indicate that a node was about to malfunction, was malfunctioning, or has malfunctioned. In order to accomplish this objective a wireless sensor network was configured to collect external metrics about the environment being monitored and internal metrics about the sensor nodes themselves. External metrics included temperature, relative humidity, and light; internal metrics included received signal strength and current draw. Over the course of the project, the design team configured a wireless sensor network, developed software to process the sensor network data in real time, display the data in a user friendly manner, and alert operators of problems in the network. A graphical user interface was written from scratch in Python with the help of external libraries wxPython and matplotlib. The software architecture leveraged the model-view-controller design pattern. Additionally, a number of algorithms were implemented in order to detect failing nodes. These algorithms include short term, long term, and zero value analysis of real time sensor data. The software was designed for use in real-time and demonstration modes in order to rigorously test and verify proper detection of failing nodes. Ultimately, the design team successfully met requirements and developed a robust application extensible for further development.

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# 1 | INTRODUCTION AND BACKGROUND

## INTRODUCTION

Wireless sensor networks are commonly used to monitor important environmental information such as temperature or light level which may alert users of hazardous conditions for themselves or machinery. However, wireless sensors typically have very limited power and memory and consequently node malfunction or failure was common. A network of largely malfunctioning nodes can mislead users analyzing the data of the network and may lead to dire consequences. Thus, it is very important to monitor the health of the nodes in the network in order to ensure they are functioning properly. The number of properly functioning nodes has a direct impact on the health of the wireless sensor network. This project consists of configuring a wireless sensor network and monitoring a few external parameters such as environmental metrics like light, temperature, and humidity as well as internal network parameters such as sensor node current, voltage, received signal strength, RF transmission power and channel availability. Developing a diagnostic tool to monitor the health of a wireless sensor network is an application of particular interest to the United States Air Force.

## BACKGROUND

The Air Force has used wireless sensor networks for many years, but has just recently been examining ways to better monitor the health of their networks. Their work on developing a health diagnostic for wireless sensor networks did not lead to a definitive solution which led them to create an open design project for senior capstone teams. They worked with multiple sensor networks of Sun SPOT and Crossbow sensor nodes organized in a mesh network topology as shown in Figure 1. In a mesh network topology each node must be able to collect and distribute its own data and serve as a relay for other nodes in order to propagate the data throughout the network.

The main advantage of this topology includes its robustness to failing nodes, but a drawback was that the nodes consume large amounts of power in order to propagate data around the network. Once the network was implemented the Air Force needed to detect anomalies tracked by collecting metrics about the network. In order to detect anomalies and identify failing nodes, the Air Force used a number of algorithms

including side-channel analysis and thresholding. Side-channel analysis consists of using information obtained from the status of the sensors themselves to correlate parameters and determine the interconnected metrics that contribute to sensor failure. Training-based and thresholding algorithms

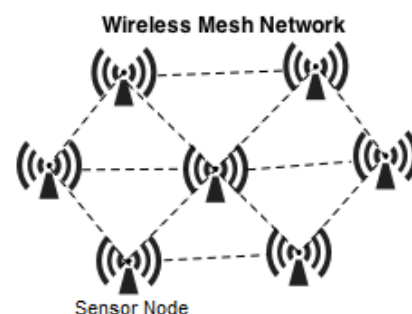


FIGURE 1. WIRELESS MESH NETWORK

work by aggregating sensor data over time to make projections based on past data and comparing those projections against incoming data. While the Air Force was not able to come to any major conclusions there has also been a lot of work done with sensor network health in industry and other branches of government.

Upon further research, NASA's Ames Research Center also addressed the creation of intelligent wireless sensor networks. "Intelligence was defined as the capability for supporting dynamic ad-hoc self-configuring real-time sensor networks able to adapt to faults while maintaining measurement accuracy and temporal integrity." They developed an ad-hoc sensor network that integrated additional sensors for specific health monitoring functions. They also created a custom software application that was able to easily display node status as well as the environmental conditions being tracked. They periodically polled the sensor network for the data in order to dynamically display the data collected from the network in real-time. The proposed design solution will utilize some of this background knowledge to aid in the rapid deployment of a wireless sensor network diagnostic tool and in designing new analysis algorithms.

## 2 | EXPLORING THE SOLUTION SPACE AND SELECTING A SPECIFIC APPROACH

### DESIGN SPECIFICATIONS

In order to create a successful design, design specifications for the project needed to be defined. Upon close examination the project description and discussions with the Air Force Research Lab sponsor, a successful project requires (i) the configuration of a wireless sensor network, (ii) low power sensor nodes, (iii) reliable communication within the network, and (iv) accurate sensor node measurements . Additional desirable requirements include (v) simple network configurability, and (vi) development of a graphical user interface.

#### A. MUST BE SATISFIED

##### I. FULLY CONFIGURED WIRELESS SENSOR NETWORK

To begin on the project, a wireless sensor network must be established. This includes sensor nodes that monitor external and internal measurements, a cluster head, and working communication between the nodes over an established protocol. The external measurements that will be monitored must include but not limited to temperature, humidity and light. Also a network topology must be decided. This parameter of the project was absolutely necessary.

##### II. LOW POWER SENSOR NODES

A node must be able last sufficiently long while deployed which includes tasks such as collecting accurate data and transmitting a high fidelity signal to the cluster head. In order to accomplish these tasks for a

long period of time the node must be low powered. Sensor nodes with long lifetime will decrease collection errors and ultimately allow for greater accuracy in nodal failure detection. This parameter was very important.

### III. RELIABLE COMMUNICATION WITHIN THE NETWORK

To assist in determining if a node or sensor is failing, the data that is retrieved by the cluster head and analyzed in the mainframe computer must be accurate. Signal accuracy is a combination of signal transmission power, received signal strength, and communication protocol. Data fidelity is highly important in order to develop reliable metrics that diagnose the health of the network. This parameter was also very important to the customer.

### IV. ACCURATE SENSOR NODE MEASUREMENTS

The sensor node must be able to communicate not only reliable, but also with accurate data. This includes external metrics such as temperature, light, humidity, etc., but also internal metrics about the nodes, such as current, and received signal strength. These metrics will monitor the environment the network was deployed in and also track relevant data about the health of each sensor node itself. These metrics are the crux of the project goal and are a crucial design parameter.

### B. INCREASES DESIGN DESIRABILITY

### V. SIMPLE NETWORK CONFIGURATION

It was particularly desirable to choose a network design that was easy to setup and configure. A network that can scale up to handle more sensor nodes was another desirable feature. This will allow the customer to customize the sensor network at any point during its lifetime. Easy set up and customization of the network was an important part of the project and very desirable to the customer.

### VI. DEVELOPMENT OF A GRAPHICAL USER INTERFACE

A visually appealing graphical user interface that displays the data obtained from the sensor network should be developed to allow an operator to quickly solve problems when they arise. A graphical user interface will make it easier to pin point what is going on in the network at all times. This will help when failing nodes are identified. This part of the project isn't necessarily required, but a user-friendly visual would significantly increase the desirability. A diagnostic tool is only useful if it is easy to use and with a handy graphical user interface it will allow an operator to easily diagnose problems within a network.

### FAST DIAGRAM

The Function Analysis System Technique (FAST) Diagram is a method to determine the essential functions of a design. The FAST Diagram in Figure 2 shows from left to right the primary and secondary functions



of a great design for this project. Reading from left to right, the diagram explains how. For example, “How do you monitor network health?”, one must configure the network and communicate the data being collected by the network. The FAST Diagram made creating conceptual designs and determining essential functions much simpler.

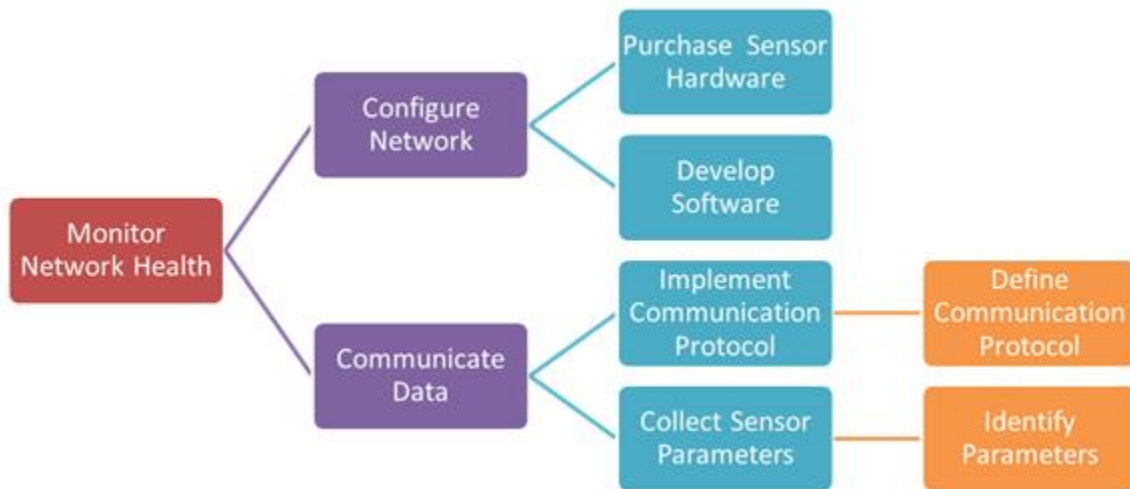


FIGURE 2. FAST DIAGRAM

## CONCEPTUAL DESIGNS

The primary focus of this project was developing a diagnostic tool to monitor the health of a network, but first network hardware must be selected. A number of hardware options were considered for the design including (a) building an entire sensor network from scratch, (b) obtaining a zigbee sensor network kit, and (c) buying a full sensor network development kit .

### A. BUILD ENTIRE SENSOR NETWORK

The first design under consideration was to build a sensor network from scratch. This included a PCB design, attached sensors, and a system-on-chip with a built in ZigBee communication protocol. In addition to this, other components would be needed to measure current draw and voltage drop in the internal circuit at each individual node.

### B. ZIGBEE NETWORK KIT

The next group of considerations was buying ZigBee communication network kit. This would require adding additional circuits for the sensors that are fed into the analog input/output port on each network node. Similarly, this group would need additional circuitry to determine internal metrics of the sensor node.

### C. SENSOR NETWORK DEVELOPMENT KIT

The last group of considerations was a full sensor development kit with multiple sensor nodes and a cluster head. These kits had full configured sensors as well as analog input/output ports for adding additional sensors. In addition, the kits that were considered measured internal node metrics.

### CHOSEN DESIGN SOLUTION

The team created a feasibility matrix to help identify the best hardware design. The feasibility matrix compares multiple designs to different vital parameters such as functionality, cost and time. Each design was ranked from 1-10 for each parameter then totaled for a complete score out of 30. See Table 1 below.

	<b>Design and build sensor network</b>	<b>Communication kit with sensor configuration</b>	<b>Full sensor network development kit</b>
<b>Functionality</b>	Highly dependent on quality of design in the given amount of time. Generally would not be as accurate because of the lack of time given and able to be put into the design. Lacked a cluster head design.  Feasible (2/10)	Be effective in communicating easily between node and cluster head with simple analog signals. Still need a circuit design for internal metrics of sensor.  Feasible (7/10)	Already measures internal and external metrics with easy programmable communication chip. All sensors are verified to factory specs, and internal node measurements are able to be tracked.  Feasible (10/10)
<b>Cost</b>	With the necessary tools to program the System-On-Chip, the total cost was approximately:  \$100 for a node + \$75 for a cluster head  Feasible (9/10)	The communication kits would reduce what is needed circuit wise, however with a price of the cost of product. With this kit, only sensors are needed. Cost approximately:  \$300 for one development kit + \$50 for all the sensors needed  Feasible (8/10)	One of the full sensor development kits would fulfill all hardware requirements. Extra sensors for robust testing would be obtained. Cost is approximately:  \$1200 for development kit + \$20 for extra sensors to test  Feasible (6/10)
<b>Time</b>	Creating a complete, accurate sensor network would require a semester of work itself.  Feasible (1/10)	Having this development kit would allow for less time setting up and more time determining the metrics that cause failure. Only extra time is configuring to send correct information from sensors.  Feasible (9/10)	The full sensor kit would eliminate a lot of configuration time. Additional sensors could be added. Very easy to set up.  Feasible (9/10)

**TABLE 1. HARDWARE FEASIBILITY MATRIX**

As seen from the feasibility matrix on the previous page, using the full sensor development kit would provide the most accuracy and functionality, with quick turnaround time in order to start developing a diagnostic tool. The decision was made to do further research on full sensor network development kits

since there is a wide range available and they vary in components, ease of use, and price. Another way to choose designs was a selection matrix. The selection matrix is similar to the feasibility matrix except the basic design is already known and instead actual parts are compared. Table2 shows the comparison of multiple development kits. Each development kit was ranked on a 1, 3 or 9 basis per feature then summed and multiplied by a weighted value.

Ratings: Strong = 9 (◇) Moderate = 3 (○) Weak = 1 (□)		Selection Matrix (Conceptual Design Rankings)			
Product	Importance (1-5)	Sun SPOT (Rev8)	Crossbow(MTS400)	Powercast (P2210-Eval-01)	National Instruments Wireless Sensor Network Starter Kit
Development Kit	4	Complete Wireless Sensor Network	Sensor Board	Complete Wireless Sensor Network	Complete Wireless Sensor Network
		Rating: ◇	Rating: □	Rating: ◇	Rating: ◇
Cost(\$)	2	400.00	395.00	1295.00	1999.00
		Rating: ◇	Rating: ◇	Rating: ○	Rating: □
Programming Language	4	JAVA	LabVIEW	C Programming	LabVIEW
		Rating: □	Rating: ○	Rating: ◇	Rating: □
Type of Sensors	2	Temperature, Light, Accelerometer	Temperature, Humidity, Barometric Pressure, Light, Acceleration and Optional GPS	Temperature, Humidity, Light and Voltage	Temperature and Voltage
		Rating: ○	Rating: ◇	Rating: ◇	Rating: □
Power	5	Battery	Battery	Wireless(RF to DC)	Battery
		Rating: ○	Rating: ○	Rating: ◇	Rating: ○
Totals		94	57	141	59

The table below displays the rankings of our conceptual designs based on the ratings from the selection matrix.

Design	Powercast (P2210-Eval-01)	Sun SPOT (Rev 8)	National Instruments WSN Starter Kit	Crossbow (MTS 400)
Ranking: 1 – Best 4 – Worst	1	2	3	4

TABLE 2. SENSOR NETWORK DEVELOPMENT KIT SELECTION MATRIX

## BUDGET

At the beginning of the semester, the team was given a \$500 budget. This budget was for all essential hardware and software components for the design project. Luckily the team had the Air Force Research

Lab as a sponsor and was able to request a larger budget within the proposal. As you can see below in Table 3 the team requested a \$2,000 budget. After receiving the project proposal, the Air Force Research Lab accepted it as well as the increased budget.

Hardware/Components	Price (\$)
Powercast P2110-EVAL-01 Development Kit <sup>1</sup>	1,250
Additional Sensors (Temperature, Light, Humidity)	100
Additional Node	400
Engineering Shop Services Fees	250
Total	2,000

TABLE 3. ESTIMATED BUDGET

### PROJECT TIMELINE (GANTT CHART)

Attached at the end of the report in Appendix 3 is the original Gantt Chart for the project and an updated Gantt Chart for the actual tasks accomplished. The major difference between the two different timetables was the available time spent on different portions of the project. These time changes aside, a great deal of the project followed the original timeline with little to no issues.

## 3 | TECHNICAL DESCRIPTION OF WORK PERFORMED

### HARDWARE DESIGN

With regards to reliability, time, and scope of the project the hardware design of the sensors used in the project were bought rather than designed and built. This allowed for more time to focus on developing a diagnostic tool for determining when a sensor node was malfunctioning. However, this did not make things simple, since there were plenty of options when purchasing the sensor network and many hardware considerations had to be made. These included: choice of power, cost, getting the correct data input, accuracy of sensors, and ease of use.

When looking upon the choice of power, there were three main types that were found to be common: power adapter plugged into a source, battery powered, and RF powered. The first option of having a sensor that was plugged into a source of power was immediately abandoned since this would eliminate

the wireless factor in our project. Although the reliability of the sensor nodes would increase without the need of monitoring voltage levels, their usability would greatly decrease, and therefore not desirable. Battery powered sensors are very common amongst wireless sensors and provide a reliable form of power source, however this adds additional complexity in detecting failed nodes. As the battery decays over time, it may not provide enough voltage to give accurate readings, and all batteries are guaranteed to die at some point in time, thus the need to pay constant attention to the battery level. The third form of power, RF energy harvesting, allows for the sensors to be powered for the lifetime of the actual sensor node hardware. Energy harvesting is growing rapidly in popularity throughout low-power electronics and working on the cutting edge of technology allows the opportunity to produce new and exciting results. A downfall with of RF energy harvesting was the need to have the provided RF transmitter with a semi-clear pathway to the sensors in order to function properly.

The cost of the project is another important factor in deciding which product to purchase. In general, as price increased so did the number features included in the sensor network and with a project geared towards the initial stages of research, a reasonably priced but reliable sensor network would fulfill specifications. The sensors were required to measure both internal and external metrics, including (but not limited to) light, humidity, temperature, and either voltage or current. The sensor network that was chosen provided that, plus measuring received signal strength. These metrics worked very well with analyzing data and determining when a particular node was malfunctioning. The received signal strength in combination with voltage could help determine when a sensor was not getting the appropriate amount of power, and monitoring activity of the external sensors also helped in error analysis.

Accuracy of the sensors was also a very important in the design decision. Flawed or inaccurate data can impact failure analysis algorithms. This could result in false positives, when a node is deemed to have failed but is actual functioning properly, or false negatives, when a failed node is not detected.

Ease of use was a big factor in selecting a sensor network. The ability to set up the network and get it running quickly was a top priority. This allowed for minimal wasted time in designing and building the network itself, and maximizing the time in researching the metrics and developing a diagnostic tool.

As show previously in Table 2, the Powercast P2210-Eval-01 development kit was chosen as the best option for the AFRL network health monitoring purposes. Included in the kit were components developed and built by Powercast Co. and Microchip. The items included are shown in Figure 3 on the next page.



FIGURE 3. POWERCAST P2110-EVAL-01 DEVELOPMENT KIT

- Power and Data Transmitter (TX91501-3W-ID)
- P2110 Evaluation Board (92110-EVB)
- Patch Antennas (2)
- Dipole Antennas (2)
- Wireless Sensor Board (WSN-EVAL-01)
- Microchip 16-bit XLP Development Board (DM240311)
- Microchip MRF24J40 PICtail/PICtail Plus Daughter Board (AC164132-1)
- PICKIT Programmer/Debugger (PG164130)

#### A. POWER AND DATA TRANSMITTER (TX91501-3W-ID)

The transmitter was manufactured by Powercast Co. It is powered at 3-watts, and uses a data integrated 8dBi antenna at a center frequency of 915 MHz<sup>6</sup>. The device sends a pre-programmed transmitter ID that was received by the Powercast chip (P2110) and decoded by the microcontroller unit (MCU) on the Wireless Sensor Board<sup>6</sup>. The transmitter provides a 60 degree beam pattern for width and height<sup>8</sup>, meaning that as long as the sensor nodes are placed within the angles defined by the transmitter, the RF signal will be able to power the nodes efficiently.



FIGURE 4. POWER AND DATA TRANSMITTER

#### B. MICROCHIP 16-BIT XLP DEVELOPMENT BOARD (DM240311)

This board, included in the Powercast P2110-Eval-01 kit, was a development platform featuring Microchip's PIC24F MCU that was pre-programmed to operate as an access point for receiving

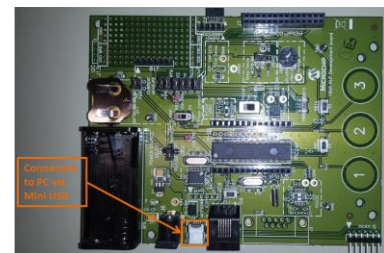


FIGURE 5. 16-BIT XLP DEVELOPMENT BOARD



data from the included Wireless Sensor Boards<sup>6</sup>. This board was connected directly to the computer via a USB cable and acts as the cluster head for all sensor nodes.

#### C. MICROCHIP MRF24J40 PICTAIL/PICTAIL PLUS DAUGHTER BOARD (AC164134-1)

A radio (2.4GHz, IEEE 802.15.4) that plugs into the 16-bit XLP Development Board for receiving data from the Wireless Sensor Boards<sup>6</sup>.

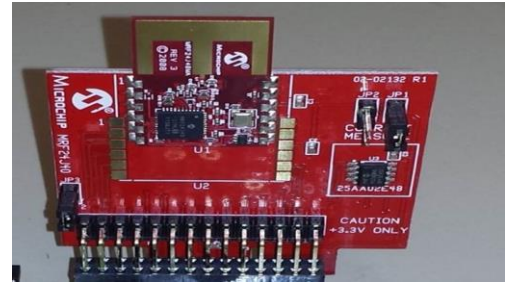


FIGURE 6. MRF24J40 PICTAIL

#### D. P2110 EVALUATION BOARD (P2110-EVB)

This component was an evaluation board (Rev. B) for the P2110 Powerharvester Receiver<sup>6</sup>. Located on the evaluation board there was an SMA connector in order to connect antennas for data transmission and a 10-pin connector for the included Wireless Sensor Boards<sup>6</sup>. Two evaluation boards are available within the kit. As mentioned above, this WSN utilizes RF energy thus; the evaluation boards are battery-free. The RF energy captured was converted to DC power, via the P2110 Powerharvester Receiver, and the DC power was stored in a 50mF capacitor. Upon reaching a voltage of 3.3V, the capacitor discharges the energy and transmits the data to the host<sup>7</sup>.



FIGURE 7. P2110 EVALUATION BOARD

#### PATCH AND DIPOLE ANTENNAS

Both antenna types are 915 MHz directional antennas<sup>6</sup>. The patch antenna has a 120-degree reception pattern whereas the dipole antenna has a 360-degree reception pattern<sup>6</sup>. Two of each type of antenna are included in the kit; one for each evaluation board (P2110-EVB).

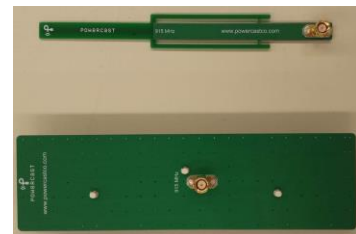


FIGURE 8. PATCH AND DIPOLE ANTENNA

#### E. WIRELESS SENSOR BOARD (WSN-EVAL-01)

This board comes fixed with 3 different sensor types: temperature, humidity and light<sup>6</sup>. It also offers an external input as well for additional sensors<sup>6</sup>. The wireless sensor board connects into the 10-pin connector on the P2110 Evaluation Board which then sends

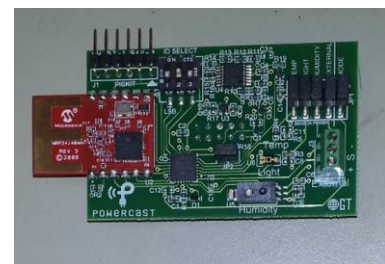


FIGURE 9. WIRELESS SENSOR BOARD

information from the sensors to the Microchip Development Board<sup>6</sup>. Two wireless sensor boards are

included in the development kit. These are the most important pieces of the kit. Analyzing the informative sent from the sensor boards to determine network health was the key objective of the project and will be discussed further throughout the report.

#### F. PICKIT 3 PROGRAMMER / DEBUGGER (PG164130)

This was a programming tool included in the kit for updating code on the Wireless Sensor Boards and the 16-bit XLP Development Board<sup>6</sup>. This was not utilized due to time constraints of the project.

### HARDWARE IMPLEMENTATION

After gaining familiarity with all of the hardware, it was time to configure the wireless sensor network development kit. Configuring the wireless network was a vital part of the design process. The team undertook many steps to setup the wireless sensor network.

The first step of configuring the network was to download and install a terminal emulator program on the PC being used. There were many options to choose from but the team decided to utilize the terminal emulator recommended by Powercast. This terminal emulator was called HyperTerminal and was available to download on Powercast's website.

The second step was to power and configure the Microchip 16-bit XLP Development Board (DM240311) as well as the Microchip MRF24J40 PICtail/PICtail Plus Daughter Board (AC164134-1). As you can see in Figure 10, The Microchip MRF24J40 was connected to the 16-Bit XLP development board via connection J7. Once both were connected, the development board settings were set. To

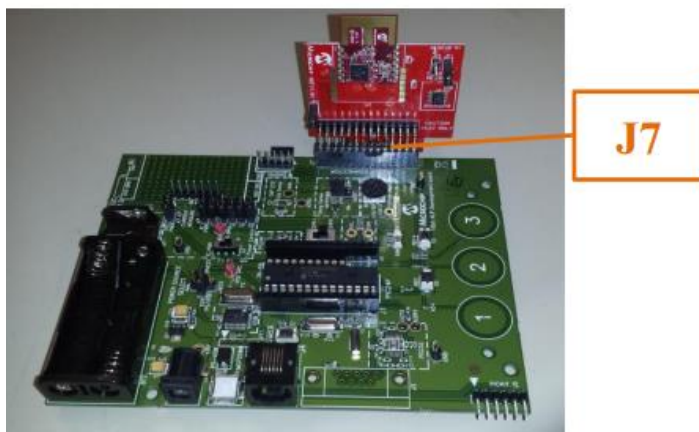


FIGURE 10. MRF24J40 CONNECTED TO DEVELOPMENT BOARD

make sure the development board was operating properly, the team had to set switch four to PIC24FK which allowed the team to configure K-series flash devices. The K-series was used for the development kit but if the 16-Bit XLP development board was bought by itself then the J-series could be used as well.

Next switch seven, the component power switch, had to be set to the ON position which allowed the component power to be selected only by the corresponding component select jumper. After switch seven was set to ON, jumper 12 had to be set to EXT PS/USB. Setting jumper 12 to EXT PS/USB allows the 16-Bit XLP development



board to be powered via USB. The USB connection provides a nominal 5V power source but by using a Schottky diode and a Low Dropout regulator circuit, the voltage was dropped down to 3.3 volts for the microcontroller and board components. After this power source was selected, the green LED on the development board was illuminated which showed the team the board was being set up correctly. Other power sources could have been used such as two AAA batteries, a CR2032 coin cell battery, or an external, regulated DC power supply. Once the power was set up a few jumpers had to be connected. Jumpers six, nine, and ten all had to be connected. Jumper six enables the modular expansion header. Jumper nine allows the team to measure current consumed by the PIC24F microcontroller but jumper nine interrupts the microcontroller's  $V_{DD}$  path so when the team was not measuring the current, jumper nine must be connected. Jumper ten acts the same way but was used to measure the current consumed by the various board components which does not include the microcontroller, ICSP header and the USB interface. After all of those jumpers were connected, the 16-Bit XLP development board was configured.

Once the development board was configured, it was time to make sure the team's PC could read the data being sent to the development board from the sensor nodes. For the team's PC to successfully read in data from the Microchip 16-Bit XLP development board, a USB-to-Serial driver file had to be downloaded and installed. Powercast's website had an available USB-to-Serial driver file on their website to download. After the file was downloaded, the team connected the development board to the PC and installed the hardware. The team now could use the port COM3 to communicate with the wireless sensor network via USB.

After the COM3 port was enabled and the development board was configured and connected to the PC, HyperTerminal was opened and configured to read in the data. HyperTerminal had a simple set up with just a few things needed to finish configuring the network. First the team had to setup the connection which included naming the connection and how the team was connecting. For this project as mentioned above, the team connected to the network via USB port COM3. Next the team had to choose the parameters of the COM3 port. With some advice from Powercast, the team chose the following settings in Table 4.

Parameter	Setting
Bits per second (Baud Rate)	19200
Data Bits	8
Parity	None
Stop Bits	1
Flow Control	Hardware

TABLE 4. COM3 PORT SETTINGS

Once the COM3 port was set, it was time to plug in the power transmitter and build the wireless sensor nodes. The power transmitter did not need any configuration. It was simple as plugging it into a normal power outlet. Next, it was time to build the wireless sensor nodes which consisted of the P2110

Evaluation Board (P2110-EVB), a dipole or patch antenna, and the Wireless Sensor Board (WSN-EVAL-01). For the team's wireless sensor network, two nodes were built using the dipole antenna.

The dipole antenna was used due to it being omni-directional. Each node also has a unique node ID which was set using DIP switches

located on each sensor board. Figure 11 shows the wireless sensor node parts as well as a completely built wireless sensor node. The last thing that needed to be done to successfully build the nodes was to make sure C5 was connected using jumper 1. C5 was a 50mF capacitor that was ideal for the development kit.

Once both nodes were built and configured and the power transmitter was plugged in, it was time to go back to the PC and make sure the development board and PC were working correctly reading the data being sent from the wireless sensor nodes. HyperTerminal was opened and the team witnessed all the data being sent from each sensor on each node to the PC via the development board successfully. See Figure 12 to view the HyperTerminal reading in data from the wireless sensor nodes.

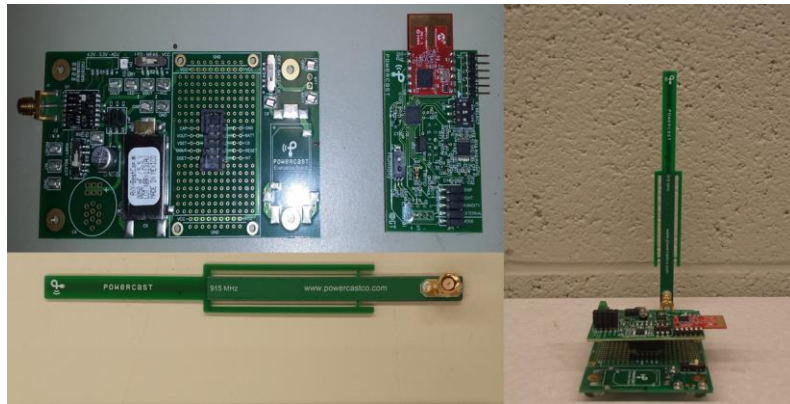


FIGURE 11. WIRELESS SENSOR BOARD COMPONENTS AND BUILT

Packet #	Time	Node	TX ID	RSSI	Temp	Humidity	Light	Extnl
38	00:04:16	2	---	2.22mW	71.8 F	31 %	145 lx	1728 mV
39	00:04:17	2	---	6.82mW	71.8 F	31 %	138 lx	1720 mV
40	00:04:18	2	242	6.40mW	71.6 F	31 %	153 lx	1742 mV
41	00:04:19	2	---	7.94mW	71.8 F	32 %	120 lx	1751 mV
42	00:04:20	2	---	4.84mW	71.8 F	32 %	113 lx	1711 mV
43	00:04:21	2	242	7.28mW	71.8 F	32 %	117 lx	1668 mV
44	00:04:23	2	242	1.74mW	71.8 F	32 %	117 lx	1736 mV
45	00:04:26	2	---	1.74mW	71.8 F	32 %	117 lx	1718 mV

FIGURE 12. HYPERTERMINAL SESSION WITH STREAMING SENSOR NETWORK DATA

## WIRELESS SENSOR NETWORK FLOW CHART

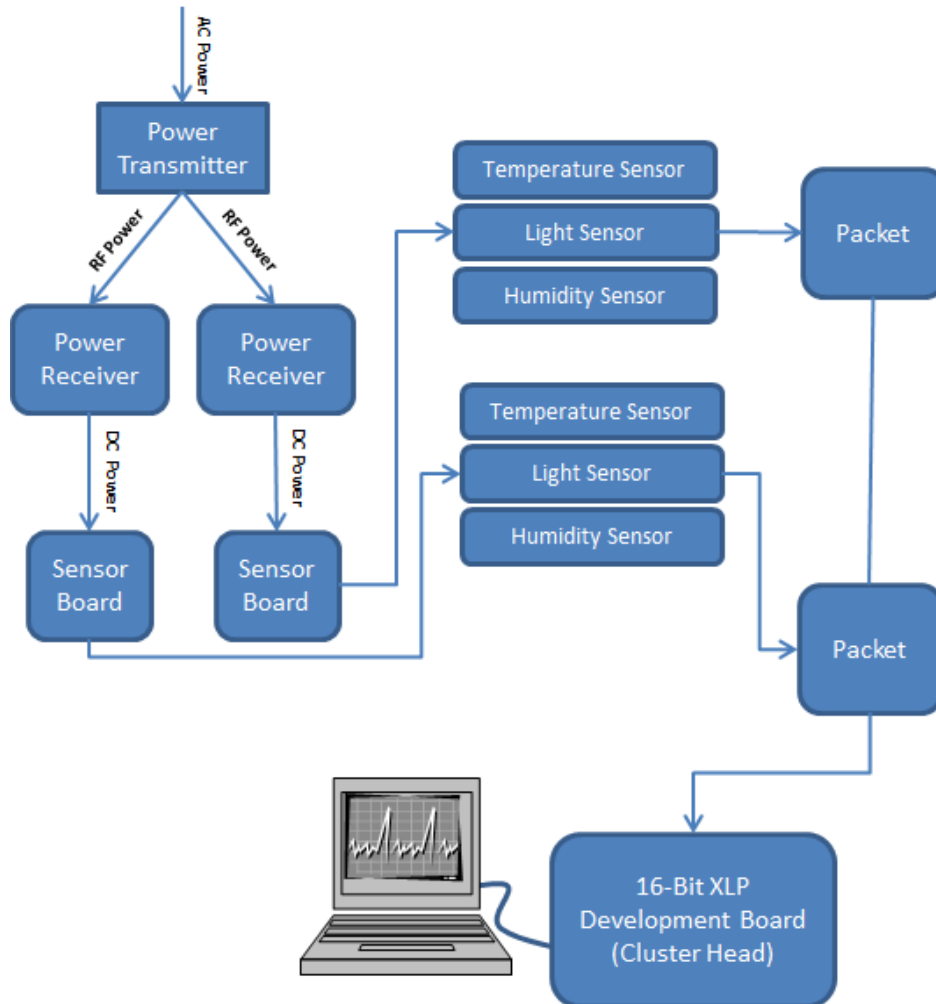


FIGURE 13. WIRELESS SENSOR NETWORK FLOWCHART

## SOFTWARE DESIGN REQUIREMENTS

The node sensor network that was purchased for this project came with the necessary software to simply run and gather data from each of the sensors in a simple manner, making setting up the sensor network less time consuming. After the network was set up to collect sensor data packets, the data had to run through processing, manipulation, and display programs. This was set up into a model-view-controller software pattern to accomplish this. The model portion does the backend data analysis, list concatenation of data, and set up all parameters to run into the view portion, which is a graphical user interface (GUI) to view the sensor data in real time.

The main software requirement embedded into the scope of the project was data representation in combination with analysis and failure detection. This visual data representation that is shown in the GUI is essential in viewing nodal failures or misrepresentation of data, as well as monitoring the health and status of the nodes themselves. This method of data representation especially assists in ease of use in the sensor nodes and also decreases the difficulty in understanding the information. The data analysis to create the failure detection is also essential in the determination of failure of nodes in the system. This software implemented into the model portion of the controller will allow users to not have to continuously monitor the system, but can look at if a failure warning is filed into the view and thus allowing less time to be consumed in graph analysis.

## SOFTWARE IMPLEMENTATION

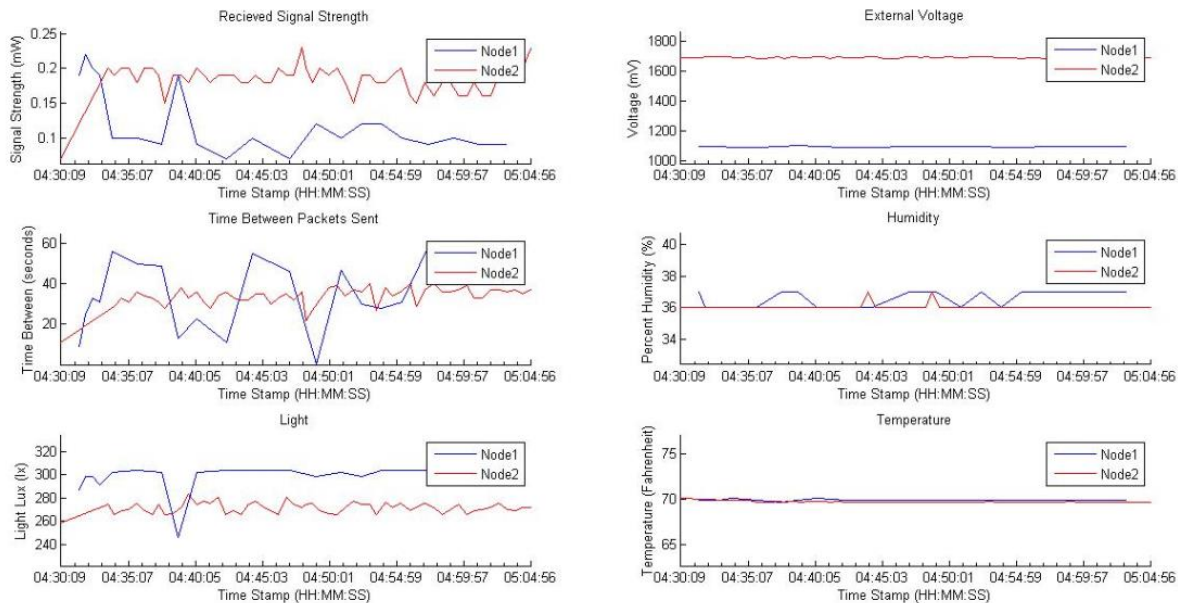
The software portion of the project grew to be the main part of the work associated with correctly analyzing the data input. First, the data is read from the USB port byte by byte into the controller module. Next, the data is formatted into packets and sent to the model for storage and data analysis. The model implements an application programming interface (API) which allows the view to access the stored data. The view polls the model for new data every few seconds and updates its view. This design



FIGURE 14. THE GRAPHICAL USER INTERFACE

pattern allows the data to be graphed in real time. The software was written in Python 2.7 [9] and required a few additional libraries including pySerial [10], matplotlib [11] and wxPython [12]. Links to more information on each of these libraries can be found in Appendix 2.

Additional algorithms were implemented for data analysis. This was done in both Python and Matlab, where the packets were read into Python which then converted the data into a comma separated value (csv) file(s) to be read from Matlab. When inputted into Matlab, correlations in the data could be viewed and graphs were easily made. Doing this allowed for easier determination of what metrics could help determine a failing sensor, assisted in looking at the data easily, and also made calculations easier to compute. An example of this data analysis from Matlab was shown below in Figure 14.

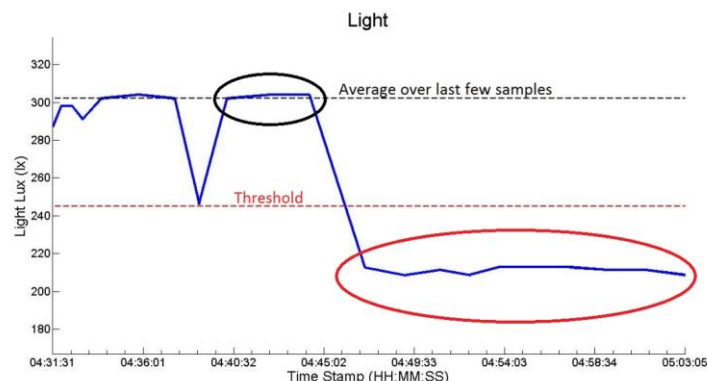


**FIGURE 15. MATLAB ANALYSIS**

The final part of the software that was implemented into this project was the failure analysis portion, also done in Python. The failures were based off of three separate functions, all determined from studying the different data types and how they react to failure. These

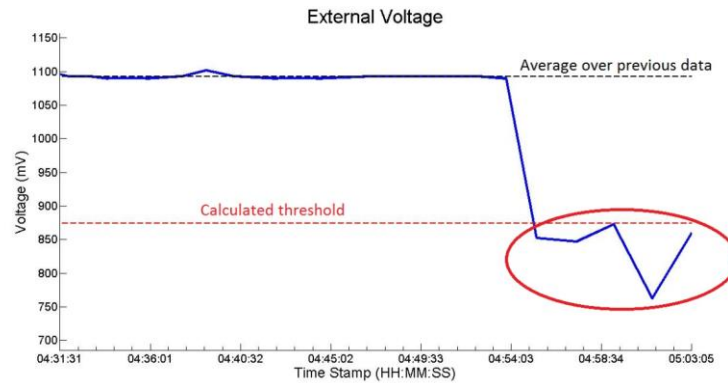
included a short term analysis, a long term analysis, and a zero data analysis. The short term analysis was used for the external sensors (measurement of light, humidity, and temperature) which took a number of the last packets and

determined if the very last one seemed out of normal. To determine what “normal” was, a calculated threshold was based off of 20% of the average of the frame except for the last packet. This formula was



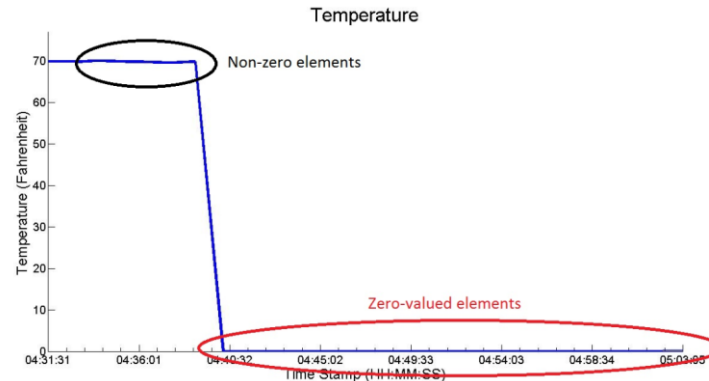
**FIGURE 16. SHORT TERM ANALYSIS**

calculated under the assumption that if one of these packets fluctuated that largely that fast, when an external factor such as that would typically not do so and generally have slow changing values, then something was not operating correctly.



**FIGURE 177. LONG TERM ANALYSIS**

The long term analysis was particularly designed for the internal sensors, which could fluctuate a good amount, however it would generally stay around the same value that it initially was. Therefore, the average of the entire data set was taken, and if a packet came in that was a certain threshold away from the calculated mean, then something occurred to make this irregularity occur.



**FIGURE 18. ZERO VALUE ANALYSIS**

Finally, a zero data analysis was a simple analysis that was implemented to see if data came in at a zero value where it was not near zero before. This was very similar to the short term analysis in terms of determining when a packet might actually read a zero value, however if it was unusual an assumption could be made of malfunction. Upon further research into sensor failure, an open circuit in the nodes resulted in no data being transferred, but rather a string of “-”, which will then be switched to a “0” value, and look like an open circuit failure.

## 4 | TEST DATA WITH PROOF OF FUNCTIONAL DESIGN

After the successful configuration of the wireless sensor network, metric analysis of the network was necessary to determine the health. Testing was split into 2 different categories, hardware functionality and software testing.

### HARDWARE FUNCTIONALITY

The tests carried out for the hardware concern the receiving of correct data packet information. The HyperTerminal, shown in Hardware Implementation, displays the readings of the sensors located on the Wireless Sensor Board. If there are issues with a particular sensor or sensors, those readings will fluctuate or become unreadable. Because of the limitations of RF energy, short distance testing was done when confirming hardware functionality. Additionally, line of sight for the transmitter and the nodes was a large factor in data retrieval for the nodes. Many sample tests were run under various conditions in order to

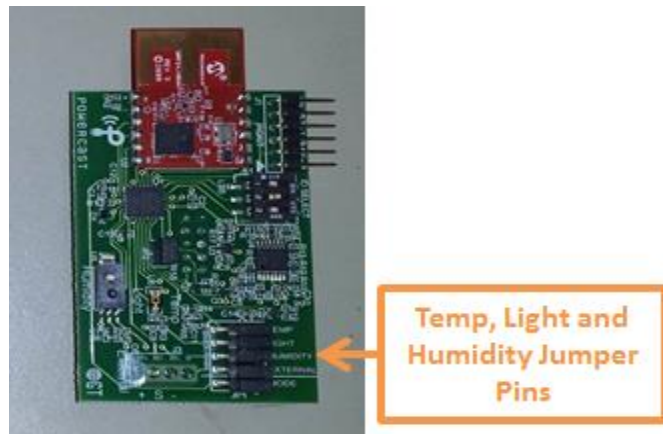


FIGURE 18. SENSOR BOARDS WITH THREE SENSORS

observe and examine the behavior of the network. The first of the tests run focused primarily on the jumper pins located on the Wireless Sensor Boards shown in Figure 19. Detailed descriptions of the tests run provide support to show “failed” sensors within the network which affect the health of the network.

### HARDWARE TESTS

All tests used both of the configured sensor nodes. Multiple parameters were changed and modified during each test such as, length of the test, removal of jumper pins from specific sensors, and angle at which the sensors were positioned in relation to the RF power transmitter. All were completed within a short distance as discussed above, in ideal environmental conditions and with the dipole antennas.

The data for all tests can be found in Appendix 4.

Test Name	Sensor Node Position (Angle in Relation to Transmitter)		Transmitter (Height & Distance from Sensor Nodes)		Sensor Status (Jumper Pins Pulled On Certain Sensors)			Test Time
	<i>Height</i>	<i>Width</i>	<i>Distance</i>	<i>Height</i>	<i>Temperature</i>	<i>Light</i>	<i>Humidity</i>	
Sample2-3	3.97°	0°	3ft	2.5 inches	Not Active	Active	Active	30 mins
Sample2-4	3.97°	0°	3ft	2.5 inches	Active	Not Active	Active	30 mins
Sample2-5	3.97°	0°	3ft	2.5 inches	Not Active	Active	Not Active	30 mins
Sample2-6	3.97°	0°	3ft	2.5 inches	Not Active	Not Active	Not Active	30 mins
Sample2-7	15.25°	0°	8ft	4ft	Active	Active	Active	45 mins
Sample2-8	0°	0°	2ft	0ft	Active	Active	Active	2 hr
Sample2-9	0°	48.5°	2.67ft	0ft	Active	Active	Active	30 mins

TABLE 5. SUMMARY OF TEST PROCEDURES

Tests sample 2-3 through 2-6 all displayed similar results. Figure 18 below gives a nice visual representation of the transmitter and sensor positions. The only difference that occurred between each test was that the data for sensors that were not active could not be displayed via the HyperTerminal. This unreadable data was displayed as such, "--" and can be seen in the test data supplied in Appendix 4. The Received Signal Strength (RSSI) varied between 0.5mW-3.5mW and time between packets (dT) averaged around 2 seconds. In order to determine the current draw of the sensors from the evaluation board, the voltage across JP2 on the Wireless Sensor Board was measured and divided by a 10Ω resistor that was in parallel for current measuring purposes<sup>4</sup>. An oscilloscope (Infiniium DSO9064A) was used to collect screen captures that show the voltage across the pin. These screen captures can be found in Appendix 4. It was found that regardless of active or non-active sensors on the Wireless Sensor Board, the current draw was constant and unchanging. The average voltage of 3.5V for the capacitor can be seen for all tests which gives a calculated average current draw of 350mA. These results were very consistent during all the tests and even with certain sensors not active, no significant change could be observed.



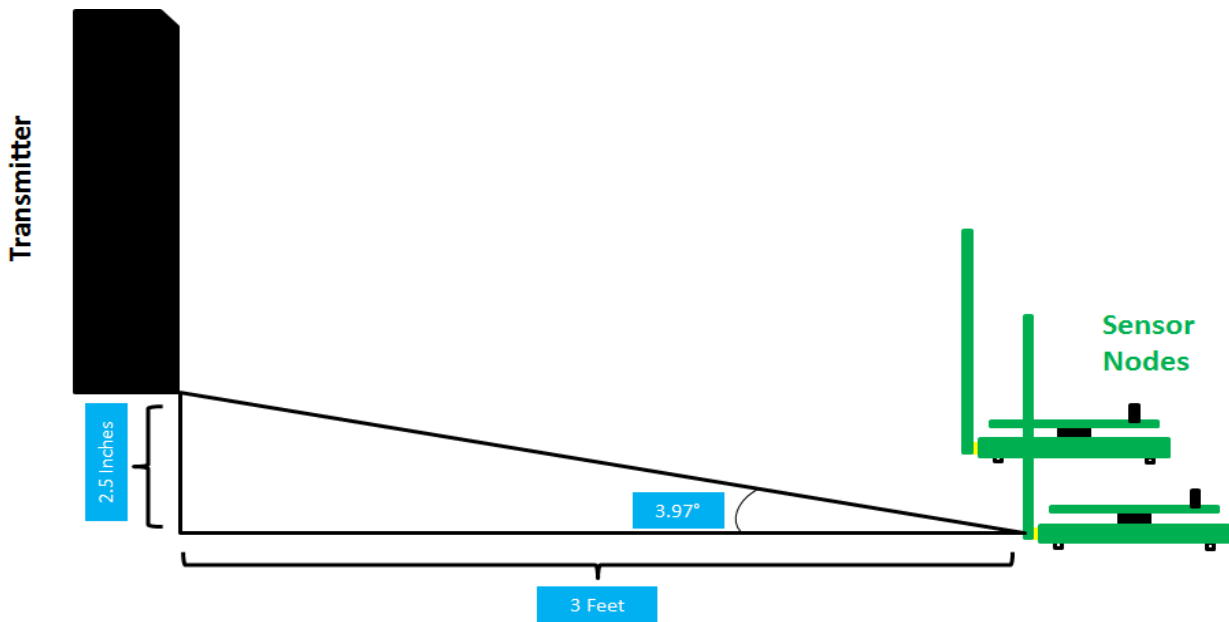


FIGURE 20. NETWORK TEST SETUP: SAMPLE2-3 THRU SAMPLE2-6

Test sample 2-7 increased the distance and height that the sensor nodes were from the transmitter and by doing so RSSI greatly decreased and dT greatly increased. These factors were expected, considering the limitations of RF energy, but the information obtained from the sensors was very consistent and matched the current conditions in the testing lab. Even though the time to receive the data had been increased, the network health was still in good despite the strength decrease.

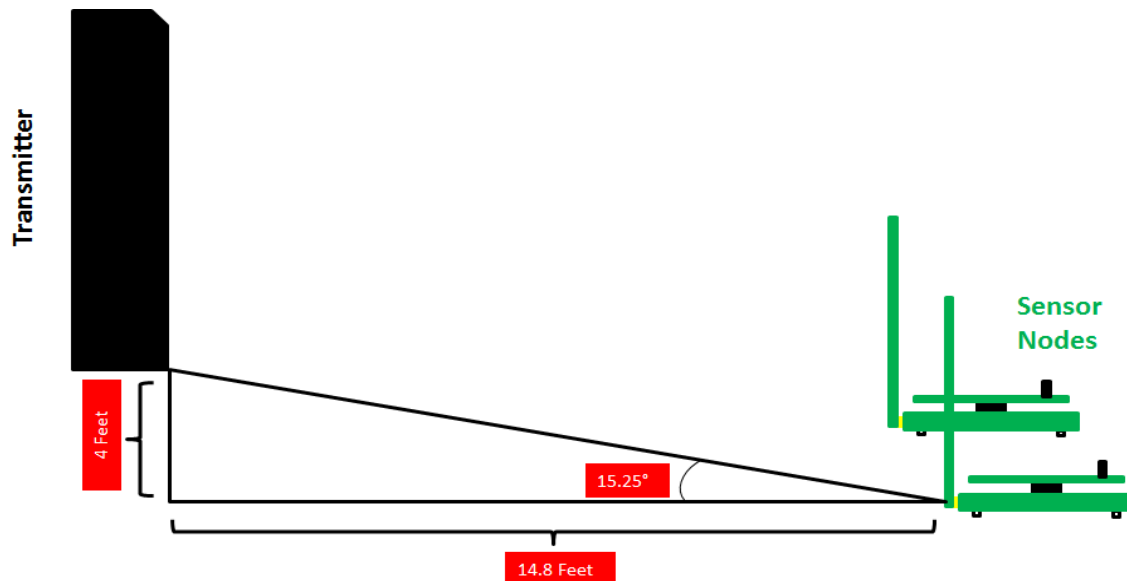


FIGURE 19. NETWORK TEST SETUP: SAMPLE2-7

Test sample 2-8 was completed specifically for the software that had not been implemented yet. It was the longest test so it could provide a large sample of data that could be displayed by the GUI interface that was being developed for it. No irregularities were found during testing and all nodes functioned properly throughout the testing period.

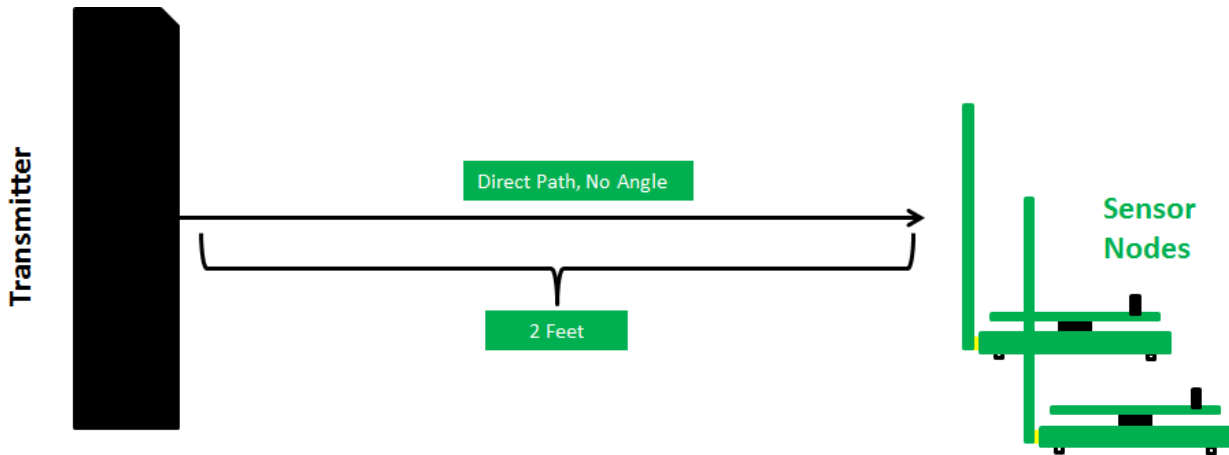


FIGURE 202. NETWORK TEST SETUP: SAMPLE2-8

The last test to be completed was sample 2-9. This test focused on the maximum width angle that was allowable from the Powercast transmitter. If the sensor nodes were placed outside of the maximum allowable angle, the capacitor would not charge and no data transmission would take place. This situation would result in a complete node failure in the network and the fact that no new data would be obtained was the clear indicator of that. This issue could easily be seen as a power issue, similar to battery life of currently used sensor nodes in the industry. Again, along with all other tests, no strange data was obtained via the HyperTerminal. All sensors were operating correctly reaffirming a good health for the network.

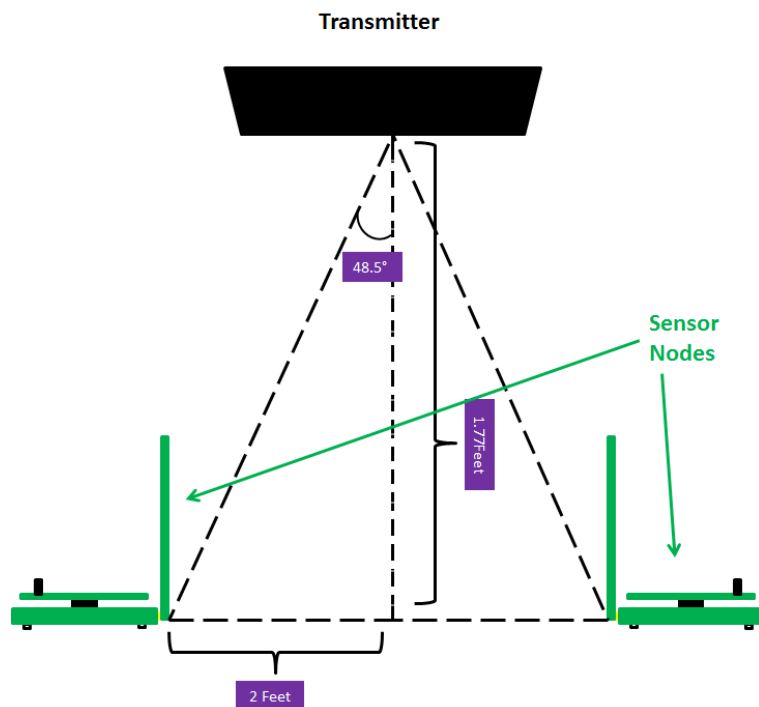


FIGURE 21. NETWORK TEST SETUP: SAMPLE2-9

## 5 | FINAL COST, SCHEDULE, SUMMARY AND CONCLUSIONS

### FINAL COSTS

As discussed before, Team 2 was granted an increase budget of \$2000 for this project. Although the budget was \$2000 the team was able to successfully complete the project with less than two-thirds of that amount. As you can see in Table 6 below, only \$1,250 of the \$2000 the team received was necessary. Luckily, the team was able to acquire everything they needed in one development kit. This helped the team keep within their budget.

Product	Cost
Powercast P2110-EVAL-01 Development Kit <sup>1</sup>	\$1,250
<b>Total</b>	<b>\$1,250</b>

TABLE 6. FINAL COSTS

### SCHEDULE

The schedule consisted of the initial project acceptance phase, research and design choices, and lastly network implementation. At the beginning of the semester the team had to decide what direction to take the project in regards to the design choices. This was due to the fact that the Air Force Research Laboratory required an additional proposal, separate from that of the ECE 480 course, which needed to be accepted before the team could start the design process. After acceptance, the team was able to obtain the necessary budget which allowed them to enter the research and design choices phase of the project. During this phase, the team obtained a suitable wireless sensor network development kit for network health monitoring purposes. Once the network was configured, the team was able to test the network, implement their software and introduce a graphical user interface. This allowed them to monitor the health of the wireless sensor network in real time. The team was pleased that they were able to stick to the schedule and meet all deadlines. The phases described above can be seen in more detail in the Final Gantt Chart in Appendix 3.

### CONCLUSION

Overall, the project was a success. Various design issues were identified earlier in the process and properly addressed. These design issues included selecting network hardware, choosing a flexible programming language, identifying a proper software design pattern, and pinpointing reliable metric analysis algorithms. Other project obstacles involved writing an extra proposal for the United States Air Force Research Laboratory, and being unable to contact and speak with sponsor due to job related

activities and the US government shutdown. Due to the shutdown, the team was unable to receive any design components previously used by the Air Force Research Laboratory.

Starting delays aside, the team was still able to proficiently analyze multiple design choices. The team decided to purchase a full wireless sensor network development kit in order to strengthen its focus on analyzing metrics within the wireless sensor network that would best determine its health. Furthermore, using a development kit allowed for quick setup and configuration. In choosing this option, the team made a great decision and was able to create a full working prototype on time and on budget.

Along with fulfilling all of the design requirements, the team was able to design and develop a project with a solid foundation for future improvements. Since the wireless sensor network is easily configurable, a future team can easily pick up where this design team left off. The software is written in Python, a simple and flexible programming language, and is well documented and engineered for future expansion. More features on graphical user interface can be added by fully leveraging the capabilities of the wxPython and matplotlib libraries. Additionally, new algorithms for network health analysis can be implemented in the model module. Overall, the project is readily suitable for future development.

The project that was chosen by the team resulted in an outstanding learning experience for each member. The team was fully immersed in the design process and each member will take with them a new set of skills to industry. Some of these soft skills include learning how to work in a team setting, outstanding written and oral communication, overcoming and learning from failures, and technical skills such as programming and configuring hardware. Ultimately, this design class taught each member how to become a professional and skills to utilize in their future careers.

## APPENDIX 1 – TECHNICAL ROLES, RESPONSIBILITIES AND WORK ACCOMPLISHED

### KELLY DESMOND – SENSOR NETWORK CONFIGURATION AND MAINTENANCE

Kelly's technical role this semester was Sensor Network Configuration and Maintenance. With this role Kelly had to make sure the team was ordering the correct wireless sensor network development kit as well as be in charge of all the hardware of that network throughout the entire semester.

His first role was to make sure that the development kit that was being purchased by the team had could successfully fulfill all the requirements from the Air Force Research Laboratory. These requirements included low power, must include but not limited to temperature, humidity and light sensors, and the team must be able to monitor internal and external parameters. Kelly was able to find the P2110-EVAL-01 Lifetime Power Energy Harvesting Development Kit for Wireless Sensors manufactured by Powercast and Microchip.



Once the development kit arrived, Kelly had to learn everything about it. He had to know what each part was and how each part connected so that the group could easily construct and deconstruct the network quick and efficiently for tests. Before the team could start the tests, Kelly had to configure the network. He had to ensure proper construction of the network and make sure it could communicate correctly with the PC. A terminal emulator needed to be downloaded, installed and setup for this purpose.

HyperTerminal, a terminal emulator from Powercast, was recommended and after some research deemed to be the best option. Kelly used HyperTerminal to set up the COM3 port on the PC so that the network would be able to send its data to the PC to be recorded.

Once the network was configured, the team needed to know how to interact with the hardware to help create different tests and read different information such as current being used by the microcontroller, the current used by the sensors, or knowing what jumpers to pull for each sensor. There were a multitude of switches and jumpers on the development and evaluation boards which Kelly was able to learn and effectively teach to the team.

### STU ANDRZEJEWSKI – FAULT DETERMINATION AND SYSTEMATIC FAILURE OF NODES

Stu's technical role comprised of network testing and fault determination.

He created multiple test procedures and implemented node failures in order to analyze the network health. These test procedures included but were not limited to, targeted sensor failures, sensor distance testing and RF signal strength in relation to network health. The forced failures of specific sensors on the Wireless Sensor Boards were done with the express interest to effects it would have on the network. During each test, Stu recorded many different parameters important to the testing procedure. These different parameters included the number of active nodes, the number and type (Light,



Temperature and Humidity) of active and failed sensors, the RF power transmitter angle in relation to the sensor nodes, the distance of the sensors from the RF power transmitter and the antenna type that were attached to each sensor node. Due to the limits of the project budget, a total of 2 sensor nodes were available and Stu utilized both of these sensor nodes for a vast majority of his tests. During his testing, he was able to successfully determine the current draw for the Wireless Sensor Boards attached to each node and collected multiple screenshots to confirm this. The most challenging part for Stu during testing was the fault determination. Because of the RF energy source, testing had to be done as close distances. If nodes were not within range of the RF power transmitter, complete failure of the node would occur and no data would be received. Stu did look at the possibility of physically damaging the sensor nodes because this would likely give data irregularities, but it was decided after a team discussion to not approach any testing in this fashion. Stu also assisted Kelly with some of the minor elements of the network configuration during the project.

**DAVID ROGERS – SOFTWARE ARCHITECT AND GRAPHICAL USER INTERFACE DEVELOPER**

David's technical role was designing and implementing the software associated with the diagnostic tool. This role required a solid foundation of object oriented programming knowledge. David's decision to use a model-view-controller architecture provided a foundation for rapid development of the application. He was able to successfully find and integrate the necessary libraries in order to deliver a high quality software product with the proper documentation for further development.



His controller implementation can be run in both real time mode and demo mode. In real time mode, data from the sensors is read from the cluster head over USB as it streams in. This required understanding and using the pySerial library to read bytes from a serial connection. In demo mode, previously recorded sample data can be read in from a file and simulated as if the data is streamed in real time.

He also successfully created a model API for which any view can interface to in order to display the data. The model is also extensible to be called for data analysis purposes. Most importantly, the model processes the data from the controller quickly and efficiently so that many calls to the model can be made without crashing the application.

David also created a graphical user interface, the view, so that an operator can see network data and the status of each node in real-time. The view required using matplotlib to plot the data, and using wxPython to create the rest of the user interface. The plots can be saved at any time and the time range and metric data shown can all be configured at run time. This view is very extensible and there is room left for further development.

Ultimately, David fulfilled his role with flying colors. He also set up a git repository in order to facilitate the software engineering process and track changes over the course of the project. Additionally, he implemented a logger within the software for documentation and debugging purposes. Finally, David multithreaded the design in order to have responsive view and the application can continue to run if the view crashes or is exited on accident.

### BRAD GARROD - FAILURE ANALYSIS ALGORITHM IMPLEMENTATION

Brad's technical role consisted of determining the associated metric data correlations to a nodal failure, then writing functions that can assist in failure detection. This role consisted of work in both Matlab for data analysis and python for the failure detection functions.

To analyze the data in Matlab, failure data produced by Stu was separated and put into a comma separated value file (csv) to be imported into Matlab. Once in Matlab, the data was organized into relevant sets which could then be plotted along with averages. This data analysis assisted in easier calculations of thresholds in regards to the failures. This analysis helped break the failure detections into two groups: external and internal sensors. These two groups had separate relationships to failure in themselves, but also grew in a confidence level when determining a failure.

Once the thresholds and correlations to failure were analyzed and determined, Python functions were constructed to determine when a nodal failure occurred. This in combination with the Graphical User Interface constructed by David can make failure detection much easier. In python, three simple functions were created: short term, long term, and zero analysis. These functions were all applied to separate data sets, which was determined from the Matlab analysis.

Overall, because of limitations in time and prioritizing tasks in relationship to these algorithms, the algorithms were not as robust as they could have been. These algorithms, however, gave a good basic detection of failure of the nodes and in combination with a user analysis using the interface can assure that nodal failure can be determined. In conclusion, the research into the metrics associated with nodal failure was accomplished which was the main scope of this project.





## APPENDIX 2 – LITERATURE AND WEBSITE REFERENCES

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## APPENDIX 3 – GANTT CHARTS

### ***Gantt Chart – Week 4***

Task Name	Duration	Start	Finish	Predecessors	Resource Names	Deadline
<b>Project Overview &amp; Tasks</b>	<b>9 days</b>	<b>Wed 9/4/13</b>	<b>Mon 9/16/13</b>			<b>NA</b>
First Group Meeting, Project Assignment & Initial Tasks	1 day	Wed 9/4/13	Wed 9/4/13		Brad,Stu,David,Kelly	Wed 9/4/13
Meeting Times & Scheduling	1 day	Wed 9/4/13	Wed 9/4/13		Brad,Stu,David,Kelly	NA
First Meeting w/Group Facilitator	1 day	Tue 9/10/13	Tue 9/10/13		Brad,Stu,David,Kelly	NA
Air Force Research Labortory (AFRL) Proposal	7 days	Thu 9/5/13	Fri 9/13/13	2	Brad,Stu,David,Kelly	Fri 9/13/13
Submit AFRL Proposal	1 day	Mon 9/16/13	Mon 9/16/13	5	Stu	Mon 9/16/13
GANTT Chart	2 days	Mon 9/16/13	Tue 9/17/13		Stu	NA
Pre-Proposal Due	5 days	Mon 9/16/13	Fri 9/20/13		Stu,David,Brad,Kelly	NA
Team Webpage Started	6 days	Mon 9/16/13	Sun 9/22/13		David	NA

First Contact w/Sponsor	1 day	Wed 10/2/13	Wed 10/2/13	6	Stu,David,Brad,Kelly	Wed 10/2/13
Proposal	15 days	Mon 9/23/13	Fri 10/11/13	8	Stu,David,Brad,Kelly	NA
<b>Configure Sensor Network &amp; Verify Correct Sensor Readings</b>	<b>16 days</b>	<b>Fri 10/4/13</b>	<b>Fri 10/25/13</b>	<b>6</b>	<b>Stu,David,Brad,Kelly</b>	<b>NA</b>
Research & Order Sensors/SOC	2 days	Fri 10/4/13	Mon 10/7/13		Brad	Mon 10/7/13
Study & Configuration of IEEE 802.15.4 (MiWi P2P Protocol)	7 days	Thu 10/10/13	Fri 10/18/13		David,Stu,Brad,Kelly	Fri 10/18/13
Verification of Correct Sensor Readings	6 days	Sat 10/19/13	Fri 10/25/13		Kelly	Fri 10/25/13
Design Day - Team Page Work	10 days	Mon 9/23/13	Fri 10/4/13		David,Kelly	NA
Oral Proposal Presentation Practice	10 days	Mon 9/23/13	Fri 10/4/13		Brad,Stu,David,Kelly	NA
Team Progress Report 1	5 days	Mon 10/28/13	Fri 11/1/13		Brad,Stu,David,Kelly	NA
Design Issues	24 days	Tue	Fri		Brad,Stu,David,Kelly	NA

Paper		9/17/13	10/18/13			
Team Progress Report 2 & Project Demonstration	5 days	Mon 11/18/13	Fri 11/22/13	18	Brad,Stu,David,Kelly	NA
Identify Simple Network Health Metrics	11 days	Sat 10/26/13	Fri 11/8/13	15	Brad,Stu,David,Kelly	Fri 11/8/13
Develop Graphical User Interface (GUI) for Configuring Sensor Nodes	11 days	Sat 11/9/13	Fri 11/22/13	21	Stu,Brad,David,Kelly	Fri 11/22/13
Confirm Health Diagnostics & Implement Network Security Functionality (If Time Allows)	7 days	Sat 11/23/13	Sun 12/1/13	22	Stu,Brad,David,Kelly	Sun 12/1/13
Final Reports			Wed 12/4/13		Brad,Stu,David,Kelly	NA
Design Day	1 day	Fri 12/6/13	Fri 12/6/13	23	Stu,David,Brad,Kelly	Fri 12/6/13

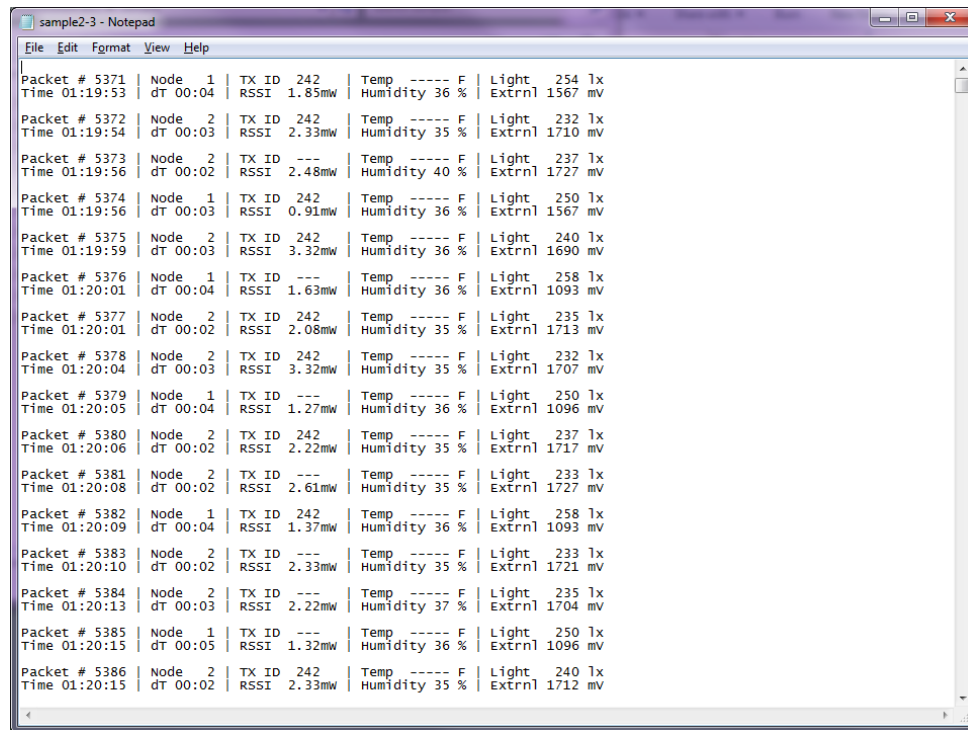
**Gantt Chart – Final**

Task Name	Duration	Start	Finish	Predecessors	Resource Names	Deadline
<b>Project Overview &amp; Tasks</b>	<b>9 days</b>	<b>Wed 9/4/13</b>	<b>Mon 9/16/13</b>			<b>NA</b>
First Group Meeting, Project Assignment & Initial Tasks	1 day	Wed 9/4/13	Wed 9/4/13		Brad,Stu,David,Kelly	Wed 9/4/13
Meeting Times & Scheduling	1 day	Wed 9/4/13	Wed 9/4/13		Brad,Stu,David,Kelly	NA
First Meeting w/Group Facilitator	1 day	Tue 9/10/13	Tue 9/10/13		Brad,Stu,David,Kelly	NA
Air Force Research Labortory (AFRL) Proposal	7 days	Thu 9/5/13	Fri 9/13/13	2	Brad,Stu,David,Kelly	Fri 9/13/13
Submit AFRL Proposal	1 day	Mon 9/16/13	Mon 9/16/13	5	Stu	Mon 9/16/13
GANTT Chart	2 days	Mon 9/16/13	Tue 9/17/13		Stu	NA
Pre-Proposal Due	5 days	Mon 9/16/13	Fri 9/20/13		Stu,David,Brad,Kelly	NA
Team Webpage	6 days	Mon	Sun		David	NA

Started		9/16/13	9/22/13			
First Contact w/Sponsor	1 day	Wed 10/2/13	Wed 10/2/13	6	Stu,David,Brad,Kelly	Wed 10/2/13
Proposal	15 days	Mon 9/23/13	Fri 10/11/13	8	Stu,David,Brad,Kelly	NA
<b>Configure Sensor Network &amp; Verify Correct Sensor Readings</b>	<b>16 days</b>	<b>Fri 10/4/13</b>	<b>Fri 10/25/13</b>	<b>8</b>	<b>Stu,David,Brad,Kelly</b>	<b>Fri 10/25/13</b>
Research & Order Sensor Development Kit	2 days	Fri 10/4/13	Mon 10/7/13		Brad	Mon 10/7/13
Verification of Correct Sensor Readings	6 days	Tue 10/8/13	Tue 10/15/13		Kelly,Stu	Tue 10/15/13
Design Day - Team Page Work	10 days	Mon 9/23/13	Fri 10/4/13		David,Kelly	NA
Oral Proposal Presentation Practice	10 days	Mon 9/23/13	Fri 10/4/13		Brad,Stu,David,Kelly	NA
Team Progress Report 1	5 days	Mon 10/28/13	Fri 11/1/13		Brad,Stu,David,Kelly	NA
Design Issues Paper	24 days	Tue 9/17/13	Fri 10/18/13		Brad,Stu,David,Kelly	NA

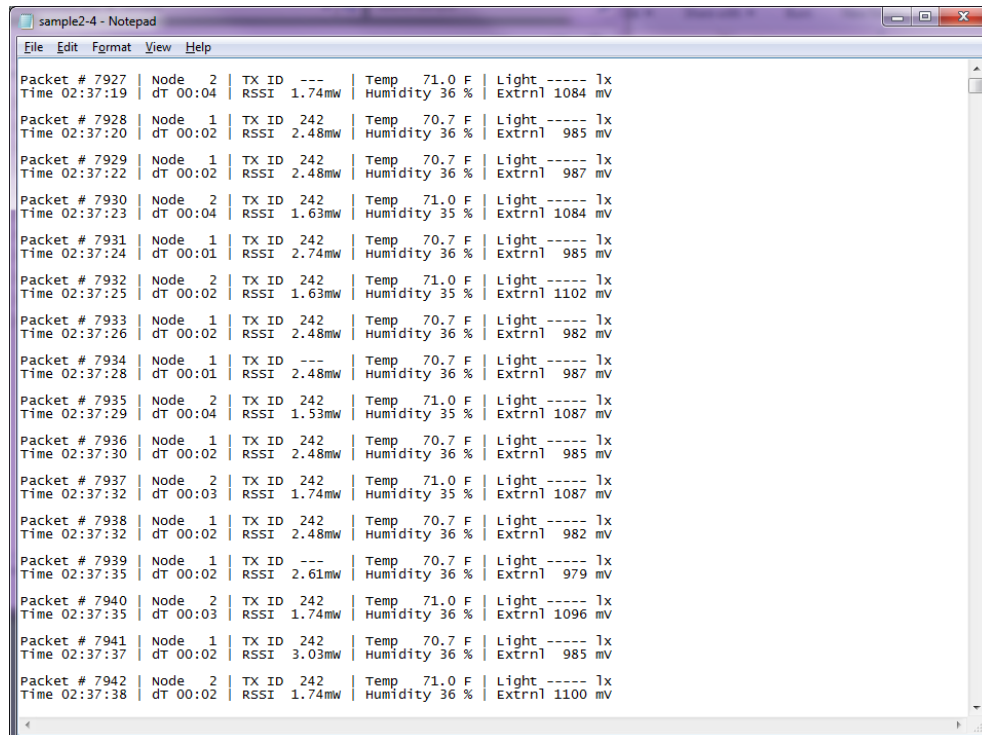
Team Progress Report 2 & Project Demonstration	5 days	Mon 11/18/13	Fri 11/22/13	17	Brad,Stu,David,Kelly	NA
Identify Simple Network Health Metrics	6 days	Tue 11/5/13	Tue 11/12/13	14	Brad,Stu,David,Kelly	Fri 11/8/13
Develop Graphical User Interface (GUI) for Configuring Sensor Nodes	11 days	Wed 11/13/13	Wed 11/27/13	20	Stu,Brad,David,Kelly	Fri 11/22/13
Confirm Health Diagnostics & Implement Network Security Functionality (If Time Allows)	3 days	Thu 11/28/13	Sun 12/1/13	21	Stu,Brad,David,Kelly	Sun 12/1/13
Final Reports			Wed 12/4/13		Brad,Stu,David,Kelly	NA
Design Day	1 day	Fri 12/6/13	Fri 12/6/13	22	Stu,David,Brad,Kelly	Fri 12/6/13

## APPENDIX 4 – TEST DATA &amp; SCREEN CAPTURES



sample2-3 - Notepad

Packet #	Node	TX ID	RSSI	Temp	Humidity	Light	Extrnl
5371	1	242	1.85mw	----- F	36 %	254 lx	1567 mv
5372	2	242	2.33mw	----- F	35 %	232 lx	1710 mv
5373	2	---	2.48mw	----- F	40 %	237 lx	1727 mv
5374	1	242	0.91mw	----- F	36 %	250 lx	1567 mv
5375	2	242	3.32mw	----- F	36 %	240 lx	1690 mv
5376	1	---	1.63mw	----- F	36 %	258 lx	1093 mv
5377	2	242	2.08mw	----- F	35 %	235 lx	1713 mv
5378	2	242	3.32mw	----- F	35 %	232 lx	1707 mv
5379	1	---	1.27mw	----- F	36 %	250 lx	1096 mv
5380	2	242	2.22mw	----- F	35 %	237 lx	1717 mv
5381	2	---	2.61mw	----- F	35 %	233 lx	1727 mv
5382	1	242	1.37mw	----- F	36 %	258 lx	1093 mv
5383	2	---	2.33mw	----- F	35 %	233 lx	1721 mv
5384	2	---	2.22mw	----- F	37 %	235 lx	1704 mv
5385	1	---	1.32mw	----- F	36 %	250 lx	1096 mv
5386	2	242	2.33mw	----- F	35 %	240 lx	1712 mv

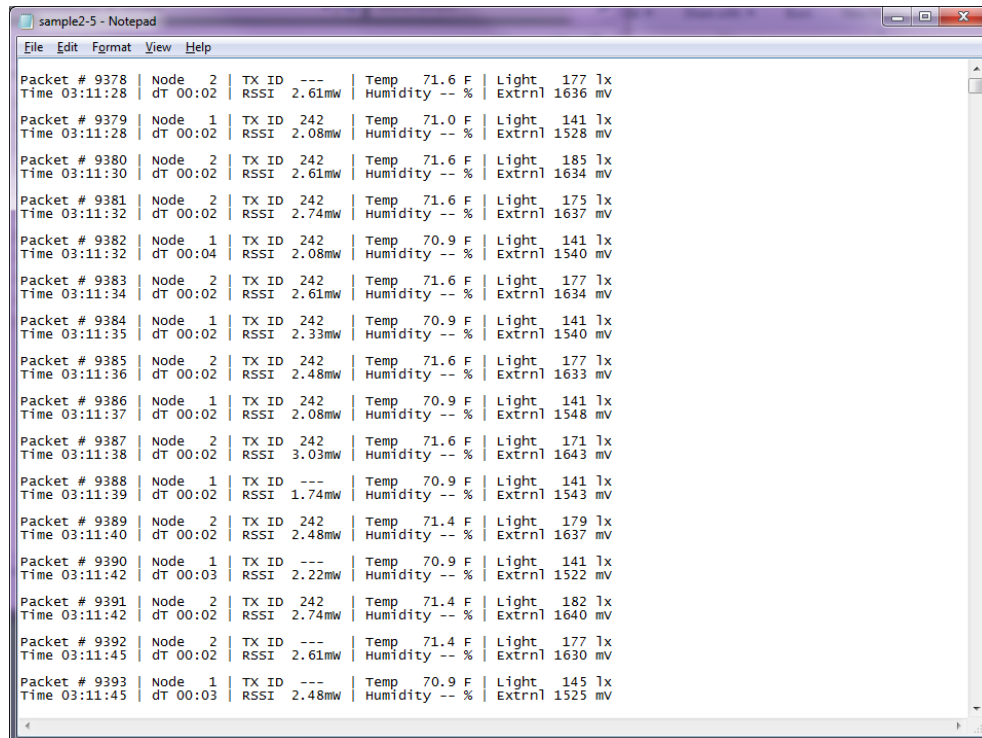
**Sample 2-3 Test Data**


sample2-4 - Notepad

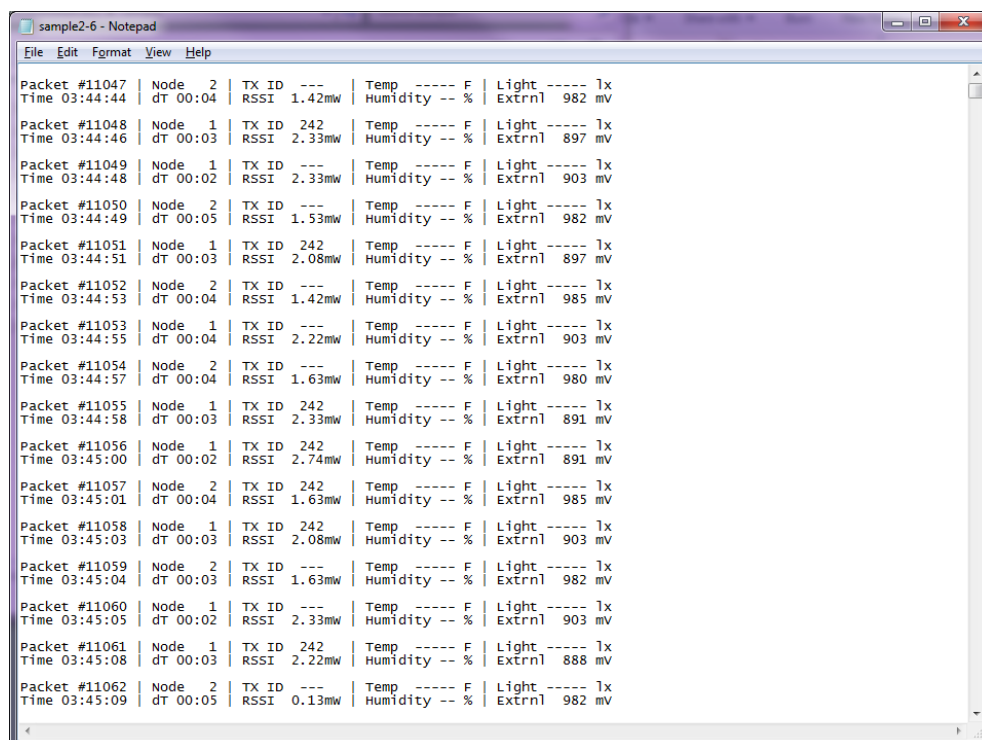
Packet #	Node	TX ID	RSSI	Temp	Humidity	Light	Extrnl
7927	2	---	1.74mw	71.0 F	36 %	----- lx	1084 mv
7928	1	242	2.48mw	70.7 F	36 %	----- lx	985 mv
7929	1	242	2.48mw	70.7 F	36 %	----- lx	987 mv
7930	2	242	1.63mw	71.0 F	35 %	----- lx	1084 mv
7931	1	242	2.74mw	70.7 F	36 %	----- lx	985 mv
7932	2	242	1.63mw	71.0 F	35 %	----- lx	1102 mv
7933	1	242	2.48mw	70.7 F	36 %	----- lx	982 mv
7934	1	---	2.48mw	70.7 F	36 %	----- lx	987 mv
7935	2	242	1.53mw	71.0 F	35 %	----- lx	1087 mv
7936	1	242	2.48mw	70.7 F	36 %	----- lx	985 mv
7937	2	242	1.74mw	71.0 F	35 %	----- lx	1087 mv
7938	1	242	2.48mw	70.7 F	36 %	----- lx	982 mv
7939	1	---	2.61mw	70.7 F	36 %	----- lx	979 mv
7940	2	242	1.74mw	71.0 F	36 %	----- lx	1096 mv
7941	1	242	3.03mw	70.7 F	36 %	----- lx	985 mv
7942	2	242	1.74mw	71.0 F	36 %	----- lx	1100 mv

**Sample 2-4 Test Data**



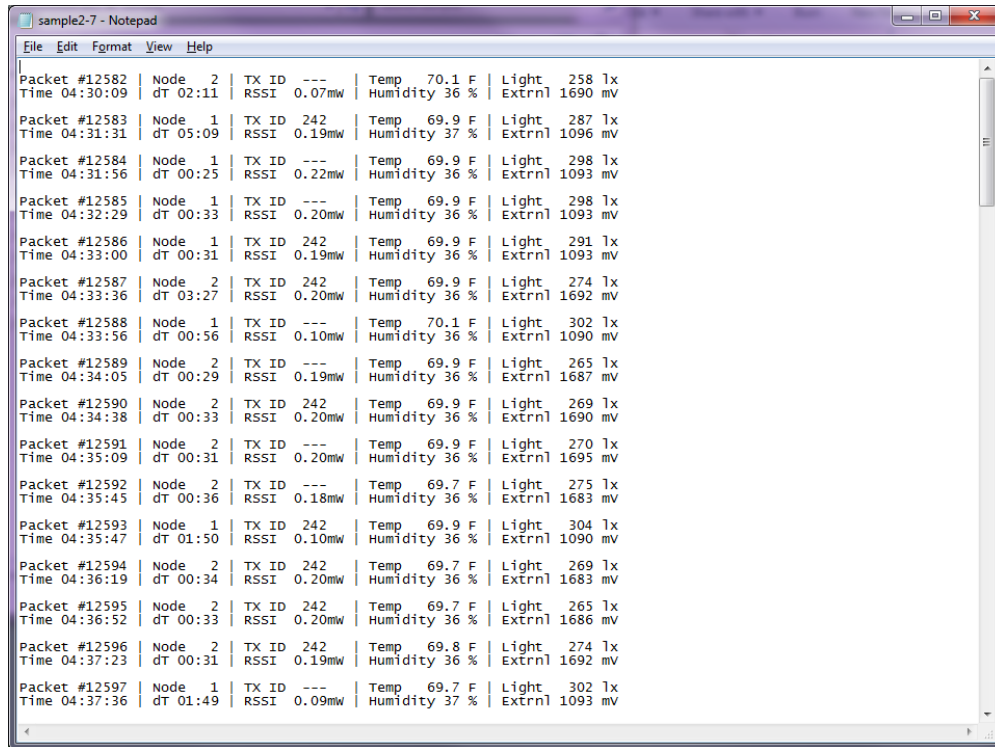


Packet #	Node	TX ID	RSSI	Temp	Humidity	Light	Extrnl
9378	2	---	2.61mw	71.6 F	-- %	177 lx	1636 mv
9379	1	242	2.08mw	71.0 F	-- %	141 lx	1528 mv
9380	2	242	2.61mw	71.6 F	-- %	185 lx	1634 mv
9381	2	242	2.74mw	71.6 F	-- %	175 lx	1637 mv
9382	1	242	2.08mw	70.9 F	-- %	141 lx	1540 mv
9383	2	242	2.61mw	71.6 F	-- %	177 lx	1634 mv
9384	1	242	2.33mw	70.9 F	-- %	141 lx	1540 mv
9385	2	242	2.48mw	71.6 F	-- %	177 lx	1633 mv
9386	1	242	2.08mw	70.9 F	-- %	141 lx	1548 mv
9387	2	242	3.03mw	71.6 F	-- %	171 lx	1643 mv
9388	1	---	1.74mw	70.9 F	-- %	141 lx	1543 mv
9389	2	242	2.48mw	71.4 F	-- %	179 lx	1637 mv
9390	1	---	2.22mw	70.9 F	-- %	141 lx	1522 mv
9391	2	242	2.74mw	71.4 F	-- %	182 lx	1640 mv
9392	2	---	2.61mw	71.4 F	-- %	177 lx	1630 mv
9393	1	---	2.48mw	70.9 F	-- %	145 lx	1525 mv

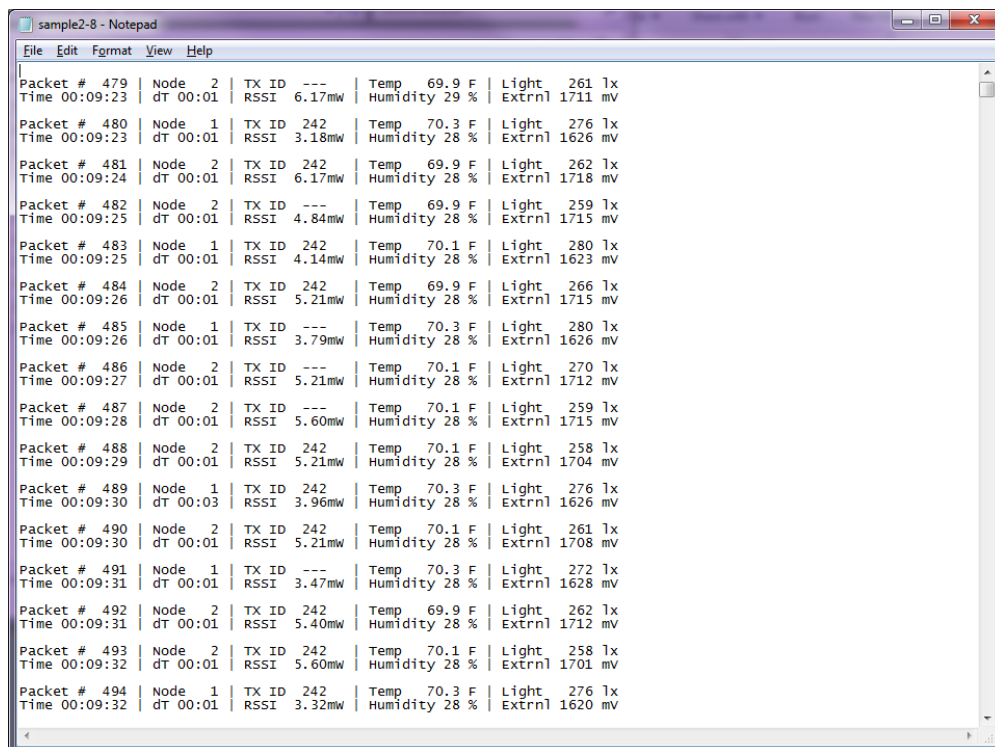
**Sample 2-5 Test Data**


Packet #	Node	TX ID	RSSI	Temp	Humidity	Light	Extrnl
11047	2	---	1.42mw	----- F	-- %	----- lx	982 mv
11048	1	242	2.33mw	----- F	-- %	----- lx	897 mv
11049	1	---	2.33mw	----- F	-- %	----- lx	903 mv
11050	2	---	1.53mw	----- F	-- %	----- lx	982 mv
11051	1	242	2.08mw	----- F	-- %	----- lx	897 mv
11052	2	---	1.42mw	----- F	-- %	----- lx	985 mv
11053	1	---	2.22mw	----- F	-- %	----- lx	903 mv
11054	2	---	1.63mw	----- F	-- %	----- lx	980 mv
11055	1	242	2.33mw	----- F	-- %	----- lx	891 mv
11056	1	242	2.74mw	----- F	-- %	----- lx	891 mv
11057	2	242	1.63mw	----- F	-- %	----- lx	985 mv
11058	1	242	2.08mw	----- F	-- %	----- lx	903 mv
11059	2	---	1.63mw	----- F	-- %	----- lx	982 mv
11060	1	---	2.33mw	----- F	-- %	----- lx	903 mv
11061	1	242	2.22mw	----- F	-- %	----- lx	888 mv
11062	2	---	0.13mw	----- F	-- %	----- lx	982 mv

**Sample 2-6 Test Data**

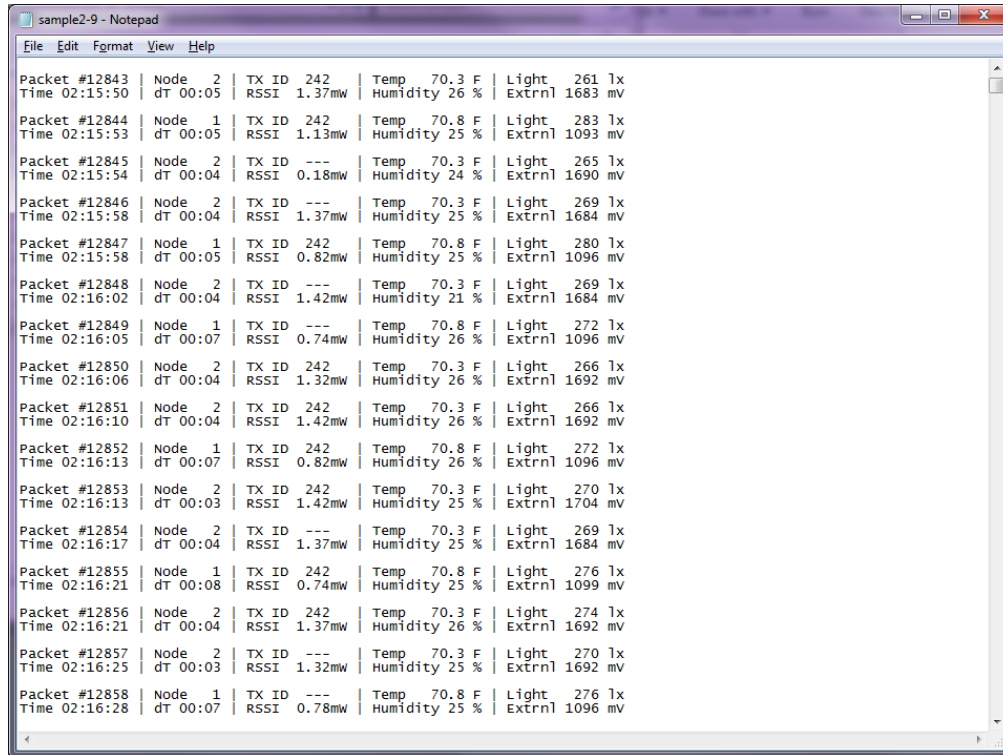


Packet #	Node	TX ID	RSSI	Temp	Humidity	Light	Extnl
12582	2	---	0.07mw	70.1 F	36 %	258 lx	1690 mv
12583	1	242	0.19mw	69.9 F	37 %	287 lx	1096 mv
12584	1	---	0.22mw	69.9 F	36 %	298 lx	1093 mv
12585	1	---	0.20mw	69.9 F	36 %	298 lx	1093 mv
12586	1	242	0.19mw	69.9 F	36 %	291 lx	1093 mv
12587	2	242	0.20mw	69.9 F	36 %	274 lx	1692 mv
12588	1	---	0.10mw	70.1 F	36 %	302 lx	1090 mv
12589	2	---	0.19mw	69.9 F	36 %	265 lx	1687 mv
12590	2	242	0.20mw	69.9 F	36 %	269 lx	1690 mv
12591	2	---	0.20mw	69.9 F	36 %	270 lx	1695 mv
12592	2	---	0.18mw	69.7 F	36 %	275 lx	1683 mv
12593	1	242	0.10mw	69.9 F	36 %	304 lx	1090 mv
12594	2	242	0.20mw	69.7 F	36 %	269 lx	1683 mv
12595	2	242	0.20mw	69.7 F	36 %	265 lx	1686 mv
12596	2	242	0.19mw	69.8 F	36 %	274 lx	1692 mv
12597	1	---	0.09mw	69.7 F	37 %	302 lx	1093 mv

**Sample 2-7 Test Data**


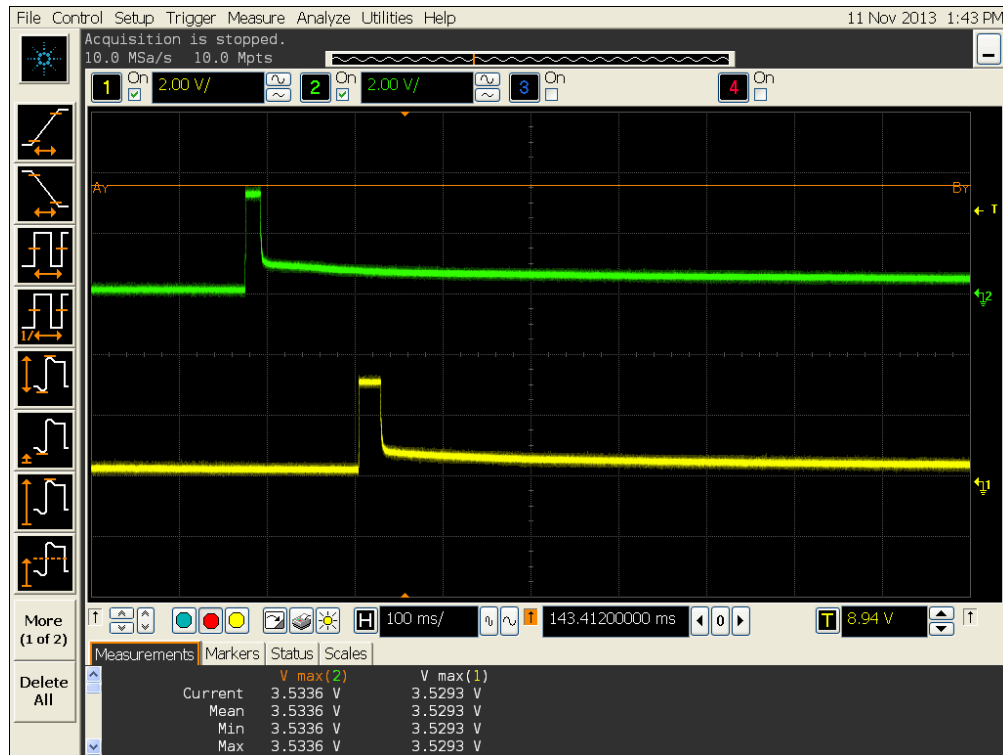
Packet #	Node	TX ID	RSSI	Temp	Humidity	Light	Extnl
479	2	---	6.17mw	69.9 F	29 %	261 lx	1711 mv
480	1	242	3.18mw	70.3 F	28 %	276 lx	1626 mv
481	2	242	6.17mw	69.9 F	28 %	262 lx	1718 mv
482	2	---	4.84mw	69.9 F	28 %	259 lx	1715 mv
483	1	242	4.14mw	70.1 F	28 %	280 lx	1623 mv
484	2	242	5.21mw	69.9 F	28 %	266 lx	1715 mv
485	1	---	3.79mw	70.3 F	28 %	280 lx	1626 mv
486	2	---	5.21mw	70.1 F	28 %	270 lx	1712 mv
487	2	---	5.60mw	70.1 F	28 %	259 lx	1715 mv
488	2	242	5.21mw	70.1 F	28 %	258 lx	1704 mv
489	1	242	3.96mw	70.3 F	28 %	276 lx	1626 mv
490	2	242	5.21mw	70.1 F	28 %	261 lx	1708 mv
491	1	---	3.47mw	70.3 F	28 %	272 lx	1628 mv
492	2	242	5.40mw	69.9 F	28 %	262 lx	1712 mv
493	2	242	5.60mw	70.1 F	28 %	258 lx	1701 mv
494	1	242	3.32mw	70.3 F	28 %	276 lx	1620 mv

**Sample 2-8 Test Data**

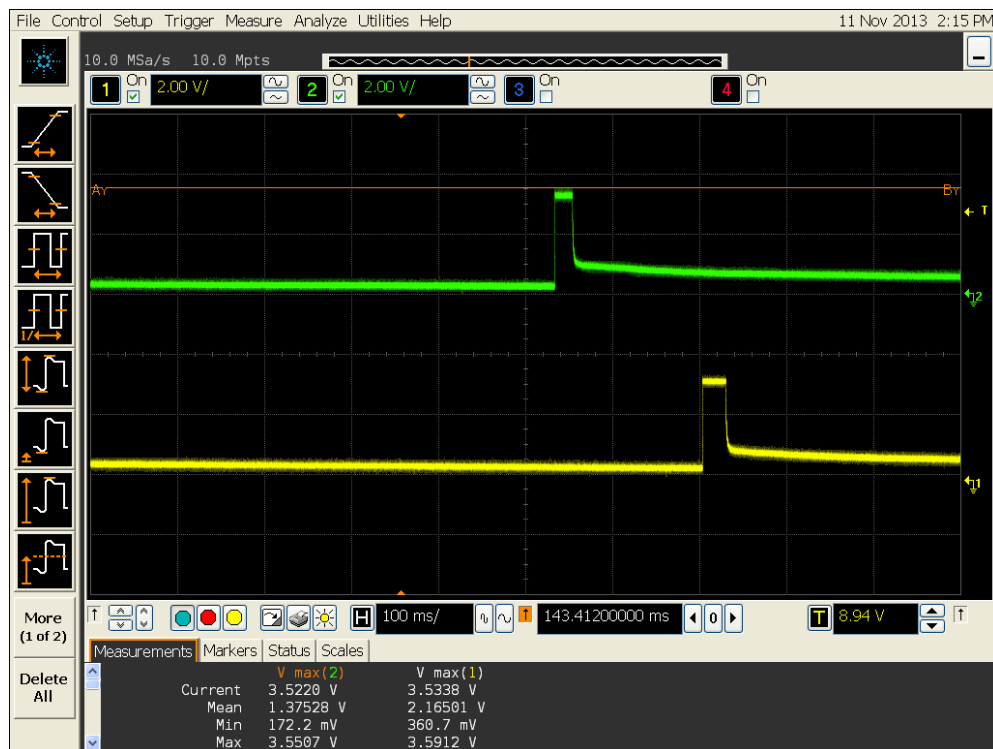


Packet #	Time	Node	TX ID	RSSI	Temp	Humidity	Light	Extrnl
#12843	02:15:50	2	242	1.37mw	70.3 F	26 %	261 lx	1683 mV
#12844	02:15:53	1	242	1.13mw	70.8 F	25 %	283 lx	1093 mV
#12845	02:15:54	2	---	0.18mw	70.3 F	24 %	265 lx	1690 mV
#12846	02:15:58	2	---	1.37mw	70.3 F	25 %	269 lx	1684 mV
#12847	02:15:58	1	242	0.82mw	70.8 F	25 %	280 lx	1096 mV
#12848	02:16:02	2	---	1.42mw	70.3 F	21 %	269 lx	1684 mV
#12849	02:16:05	1	---	0.74mw	70.8 F	26 %	272 lx	1096 mV
#12850	02:16:06	2	242	1.32mw	70.3 F	26 %	266 lx	1692 mV
#12851	02:16:10	2	242	1.42mw	70.3 F	26 %	266 lx	1692 mV
#12852	02:16:13	1	242	0.82mw	70.8 F	26 %	272 lx	1096 mV
#12853	02:16:13	2	242	1.42mw	70.3 F	25 %	270 lx	1704 mV
#12854	02:16:17	2	---	1.37mw	70.3 F	25 %	269 lx	1684 mV
#12855	02:16:21	1	242	0.74mw	70.8 F	25 %	276 lx	1099 mV
#12856	02:16:21	2	242	1.37mw	70.3 F	26 %	274 lx	1692 mV
#12857	02:16:25	2	---	1.32mw	70.3 F	25 %	270 lx	1692 mV
#12858	02:16:28	1	---	0.78mw	70.8 F	25 %	276 lx	1096 mV

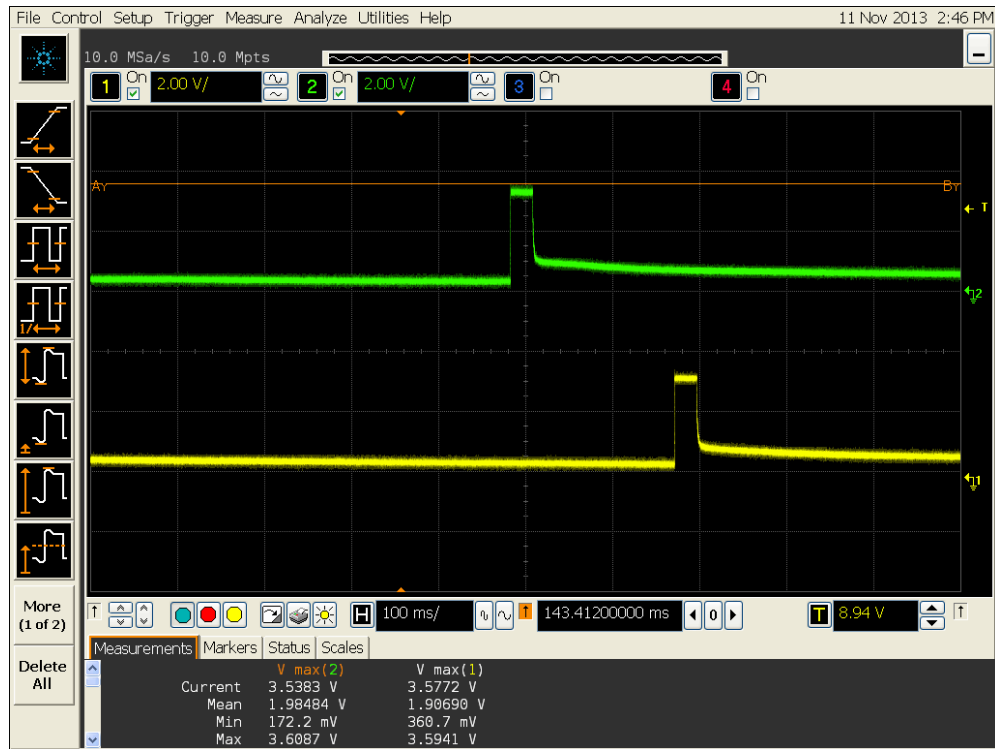
**Sample 2-9 Test Data**



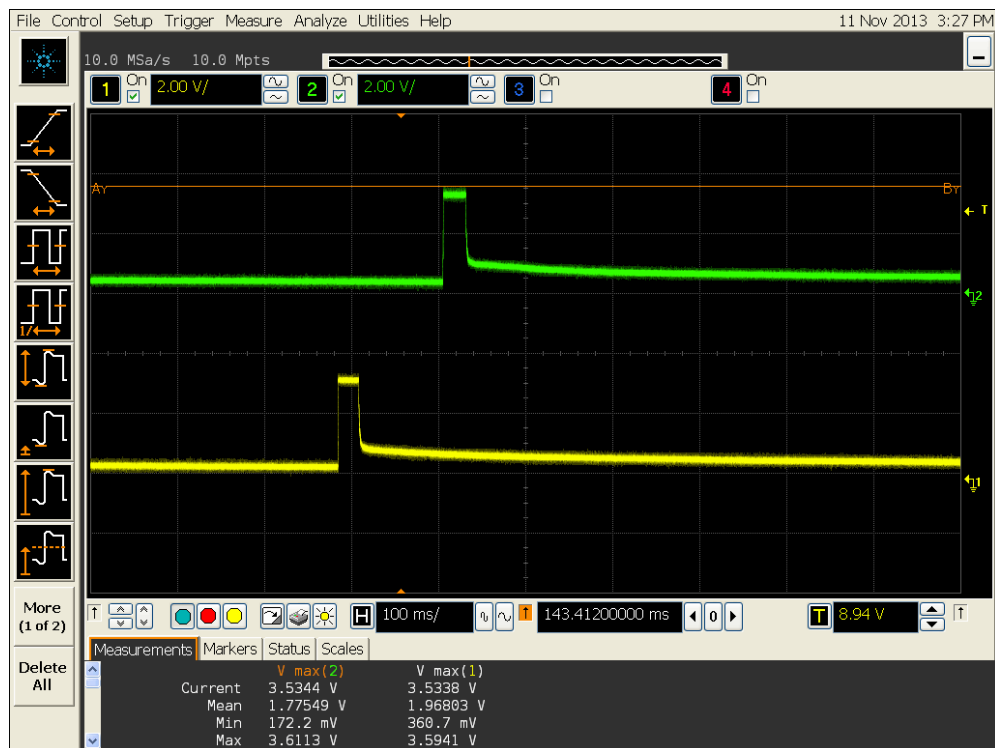
**Sample 2-3: JP2 Voltage Screen Capture**



**Sample 2-4: JP2 Voltage Screen Capture**



**Sample 2-5: JP2 Voltage Screen Capture**



**Sample 2-6: JP2 Voltage Screen Capture**