SENSORS a.k.a. Interfacing to the Real World: Review of Electrical Sensors and Actuators

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Transducers

Transducer

- a device that converts a primary form of energy into a corresponding signal with a different energy form
 - <u>Primary Energy Forms</u>: mechanical, thermal, electromagnetic, optical, chemical, etc.
- take form of a sensor or an actuator
- Sensor (e.g., thermometer)
 - a device that detects/measures a signal or stimulus
 - acquires information from the "real world"
- Actuator (e.g., heater)
 - a device that generates a signal or stimulus





Sensor Systems

Typically interested in electronic sensor

- convert desired parameter into electrically measurable signal
- General Electronic Sensor
 - <u>primary transducer</u>: changes "real world" parameter into electrical signal
 - <u>secondary transducer</u>: converts electrical signal into analog or digital values



Typical Electronic Sensor System



Example Electronic Sensor Systems

- Components vary with application
 - digital sensor within an instrument





Primary Transducers

Conventional Transducers

large, but generally reliable, based on older technology

- thermocouple: temperature difference
- compass (magnetic): direction
- Microelectronic Sensors

millimeter sized, highly sensitive, less robust

- photodiode/phototransistor: photon energy (light)
 - infrared detectors, proximity/intrusion alarms
- piezoresisitve pressure sensor: air/fluid pressure
- microaccelerometers: vibration, △-velocity (car crash)
- chemical senors: O₂, CO₂, Cl, Nitrates (explosives)
- DNA arrays: match DNA sequences



Example Primary Transducers





Displacement Measurements

- Measurements of size, shape, and position utilize displacement sensors
- Examples
 - diameter of part under stress (direct)
 - movement of a microphone diaphragm to quantify liquid movement through the heart (indirect)
- Primary Transducer Types
 - Resistive Sensors (Potentiometers & <u>Strain Gages</u>)
 - Inductive Sensors
 - Capacitive Sensors
 - Piezoelectric Sensors
- Secondary Transducers
 - Wheatstone Bridge
 - Amplifiers



Strain Gage: Gage Factor

- Remember: for a strained thin wire ٠
 - $\Delta R/R = \Delta L/L \Delta A/A + \Delta \rho/\rho$
 - $A = \pi (D/2)^2$, for circular wire



- Poisson's ratio, μ: relates change in diameter D to change in length L
 - $\Delta D/D = \mu \Delta L/L$
- Thus
 - $\Delta R/R = (1+2\mu) \Delta L/L + \Delta \rho/\rho$

dimensional effect piezoresistive effect

Gage Factor, G, used to compare strain-gate materials ٠

-
$$G = \Delta R/R = (1+2\mu) + \Delta \rho/\rho$$

 $\Delta L/L$



Temperature Sensor Options

- Resistance Temperature Detectors (RTDs)
 - Platinum, Nickel, Copper metals are typically used
 - positive temperature coefficients $R_T = R_0 |1 + \alpha_1 T + \alpha_2 T^2 + \cdots + \alpha_n T^n + | \cong R_0 [1 + \alpha_1 T]$
- Thermistors ("thermally sensitive resistor")
 - formed from semiconductor materials, not metals
- $R_{T} = R_{0} \exp \left[B\left(\frac{1}{T} \frac{1}{T_{n}}\right)\right]$ often composite of a ceramic and a metallic oxide (Mn, Co, Cu or re)
 - typically have negative temperature coefficients
- Thermocouples ٠

T_{rff}

based on the Seebeck effect: dissimilar metals at diff. temps. \rightarrow signal Connecting

	Metal A	
т.		

Metal B

ν.							
* OUT		THERMOCOUPLES	RTD	IC			
	ACCURACY	Limits of error wider than RTD or IC Sensor	Better accuracy than thermocouple	Best accuracy			
	RUGGEDNESS	Excellent	Sensitive to strain and shock	Sensitive to shock			
	TEMPERATURE	-400 to 4200° F	-200 to 1475° F	-70 to 300° F			
[DRIFT	Higher than RTD	Lower than TC				
	LINEARITY	Very non-linear	Slightly non-linear	Very linear			
	RESPONSE	Fast dependent on size	Slow due to thermal mass	Faster than RTD			
	cost	Rather inexpensive except for noble metals TCs, which are very expensive	More expensive	Low cost			



Fiber-optic Temperature Sensor

- Sensor operation
 - small prism-shaped sample of single-crystal undoped GaAs attached to ends of two optical fibers
 - light energy absorbed by the GaAs crystal depends on temperature
 - percentage of received vs. transmitted energy is a function of temperature
- Can be made small enough for biological implantation



ECE 480, Prof. A. Mason

Example MEMS Transducers

- MEMS = micro-electro-mechanical system
 - miniature transducers created using IC fabrication processes
- Microaccelerometer
 - cantilever beam
 - suspended mass





- Rotation
 - gyroscope



• Pressure







Diaphragm (Upper electrode)

Lower electrode

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Passive Sensor Readout Circuit





Operational Amplifiers

Properties

- <u>open-loop gain</u>: ideally infinite: practical values 20k-200k
 high open-loop gain → virtual short between + and inputs
- input impedance: ideally infinite: CMOS opamps are close to ideal
- <u>output impedance</u>: ideally zero: practical values 20-100 Ω
- <u>zero output offset</u>: ideally zero: practical value <1mV
- gain-bandwidth product (GB): practical values ~MHz
 - \cdot frequency where open-loop gain drops to 1 V/V
- Commercial opamps provide many different properties
 - low noise
 - low input current
 - low power
 - high bandwidth
 - low/high supply voltage
 - special purpose: comparator, instrumentation amplifier



Basic Opamp Configuration



Non-Inverting Amp

Inverting Amp













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Instrumentation Amplifier

 \sim input stage ξR_1

V1O

V2 O

- Robust differential gain amplifier
- Input stage
 - high input impedance
 - buffers gain stage
 - no common mode gain
 - can have differential gain
- Gain stage
 - differential gain, low input impedance
- Overall amplifier
 - amplifies only the differential component
 - high common mode rejection ratio
 - high input impedance suitable for biopotential electrodes with high output impedance





R₃

 $\leq R_2$

R₂

gain stage

v.

Instrumentation Amplifier w/ BP Filter



With 776 op amps, the circuit was found to have a CMRR of 86 dB at 100 Hz and a noise level of 40 mV peak to peak at the output. The frequency response was 0.04 to 150 Hz for ± 3 dB and was flat over 4 to 40 Hz. The total gain is 25 (instrument amp) x 32 (non-inverting amp) = 800.



Connecting Sensors to Microcontrollers

sensor

sensor

- Analog
 - many microcontrollers have a built-in A/D
 - 8-bit to 12-bit common
 - many have multi-channel A/D inputs
- Digital
 - serial I/O
 - use serial I/O port, store in memory to analyze
 - synchronous (with clock)
 - must match byte format, stop/start bits, parity check, etc.
 - asynchronous (no clock): more common for comm. than data
 - must match baud rate and bit width, transmission protocol, etc.
 - frequency encoded
 - use timing port, measure pulse width or pulse frequency



keypad

display

instrument

μC

signal timing

memory

Connecting Smart Sensors to PC/Network

- "Smart sensor" = sensor with built-in signal processing & communication
 - e.g., combining a "dumb sensor" and a microcontroller
- Data Acquisition Cards (DAQ)
 - PC card with analog and digital I/O
 - interface through LabVIEW or user-generated code
- Communication Links Common for Sensors
 - asynchronous serial comm.
 - universal asynchronous receive and transmit (UART)
 - 1 receive line + 1 transmit line. nodes must match baud rate & protocol
 - RS232 Serial Port on PCs uses UART format (but at +/- 12V)
 - can buy a chip to convert from UART to RS232
 - synchronous serial comm.
 - serial peripheral interface (SPI)
 - 1 clock + 1 bidirectional data + 1 chip select/enable
 - I^2C = Inter Integrated Circuit bus
 - designed by Philips for comm. inside TVs, used in several commercial sensor systems
 - IEEE P1451: Sensor Comm. Standard
 - several different sensor comm. protocols for different applications



Sensor Calibration

- Sensors can exhibit non-ideal effects
 - offset: nominal output ≠ nominal parameter value
 - nonlinearity: output not linear with parameter changes
 - cross parameter sensitivity: secondary output variation with, e.g., temperature
- Calibration = adjusting output to match parameter
 - analog signal conditioning
 - look-up table
 - digital calibration
 - $T = a + bV + cV^2$,
 - T= temperature; V=sensor voltage;
 - a,b,c = calibration coefficients
- Compensation
 - remove secondary sensitivities
 - must have sensitivities characterized
 - can remove with polynomial evaluation
 - $P = a + bV + cT + dVT + eV^2$, where P=pressure, T=temperature



offset

-30



lineal